



Scientific Day 2012

Multidisciplinary Analysis Workflow with the FlowSimulator

Lars Reimer

With contributions of

Daniel Vollmer, Gunnar Einnarson, Stefan Görtz, Thomas Gerhold,
Ralf Heinrich, Norbert Kroll, Andreas Michler,
Markus Ritter, Jens Neumann (all DLR),
Lars-Uwe Hansen (Airbus)



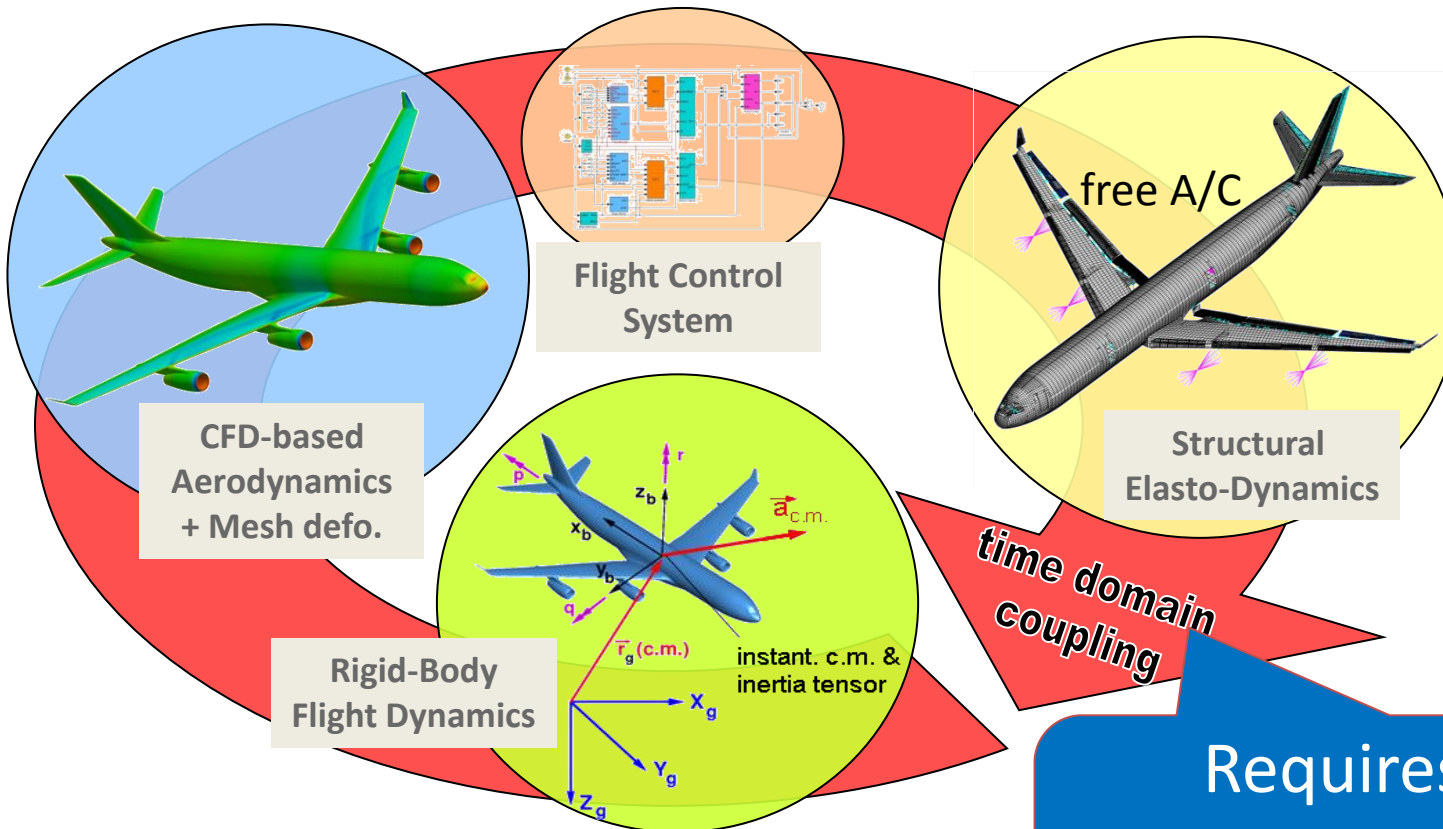
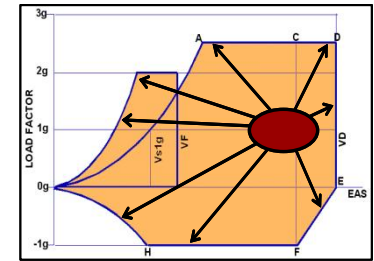
Knowledge for Tomorrow

Outline

- General overview of FlowSimulator (objectives, concept, etc.)
 - Aspects of trim simulations with FS
 - Aspects of CFD-CSM coupled simulations with FS
- } focus on
DLR
process
chains



Overall Objective: Accurate Analysis for Entire Flight Envelope



Requires Efficient
Multidisciplinary HiFi
Simulation Tools



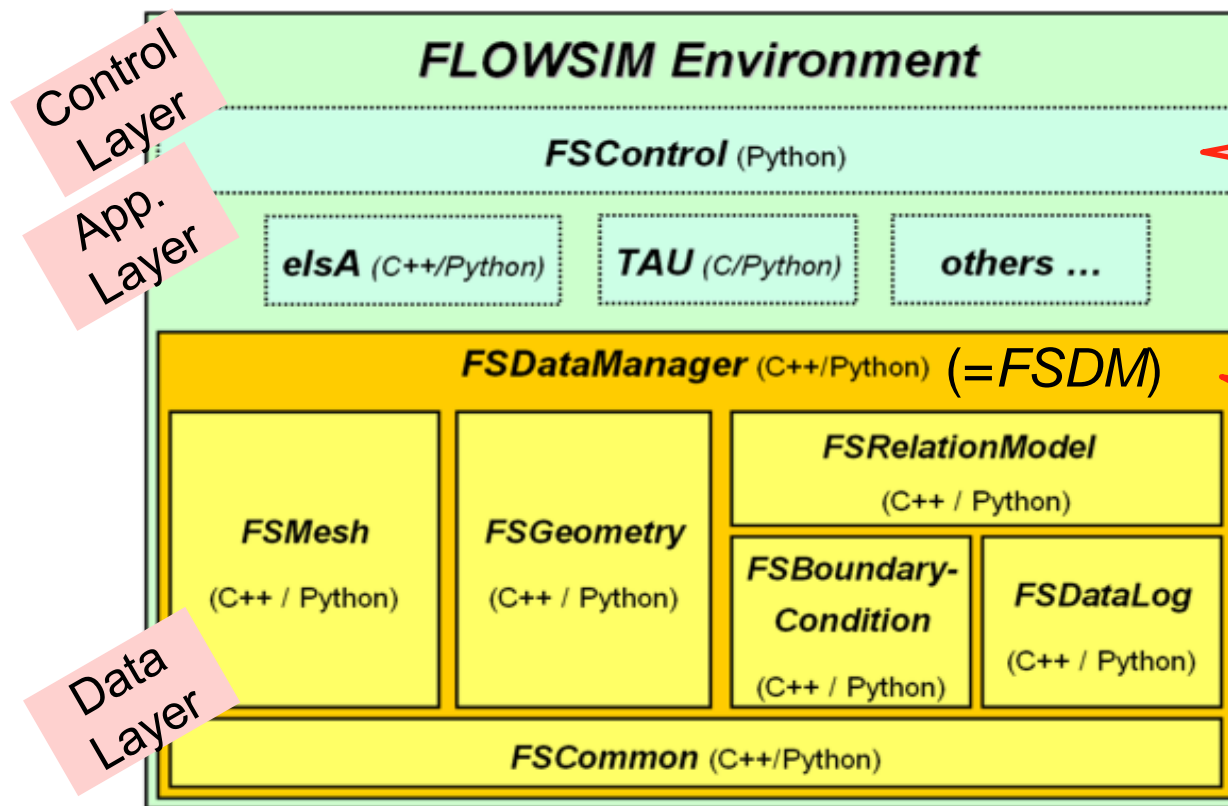
What is FlowSimulator and What Are Its Main Objectives ?

- Numerical tool box for **high-performance multi-disciplinary** simulations
- Designed for efficient massively-parallel **in-memory data exchange** between mono-disciplinary codes
- **Easy replacement** of simulation components



What is *FlowSimulator* Technically ?

- *FS* is a bundle of Python modules which work on a common data structure, i.e. the *FSDM*
- Python-based scripting layer enables rapid prototyping of tool chains



- devel. mainly by Airbus
- supposed to be main access layer for end-users (high-level classes)

- devel. by entire FS community
- open source
- provides parallel data management



GForge Server (<http://dev.as.dlr.de/gf>)



Home

Meine Sachen

Benutzer

Suche

Projekte

Schnipsel



Home » Project Durchsuchen

Check for list of existing projects

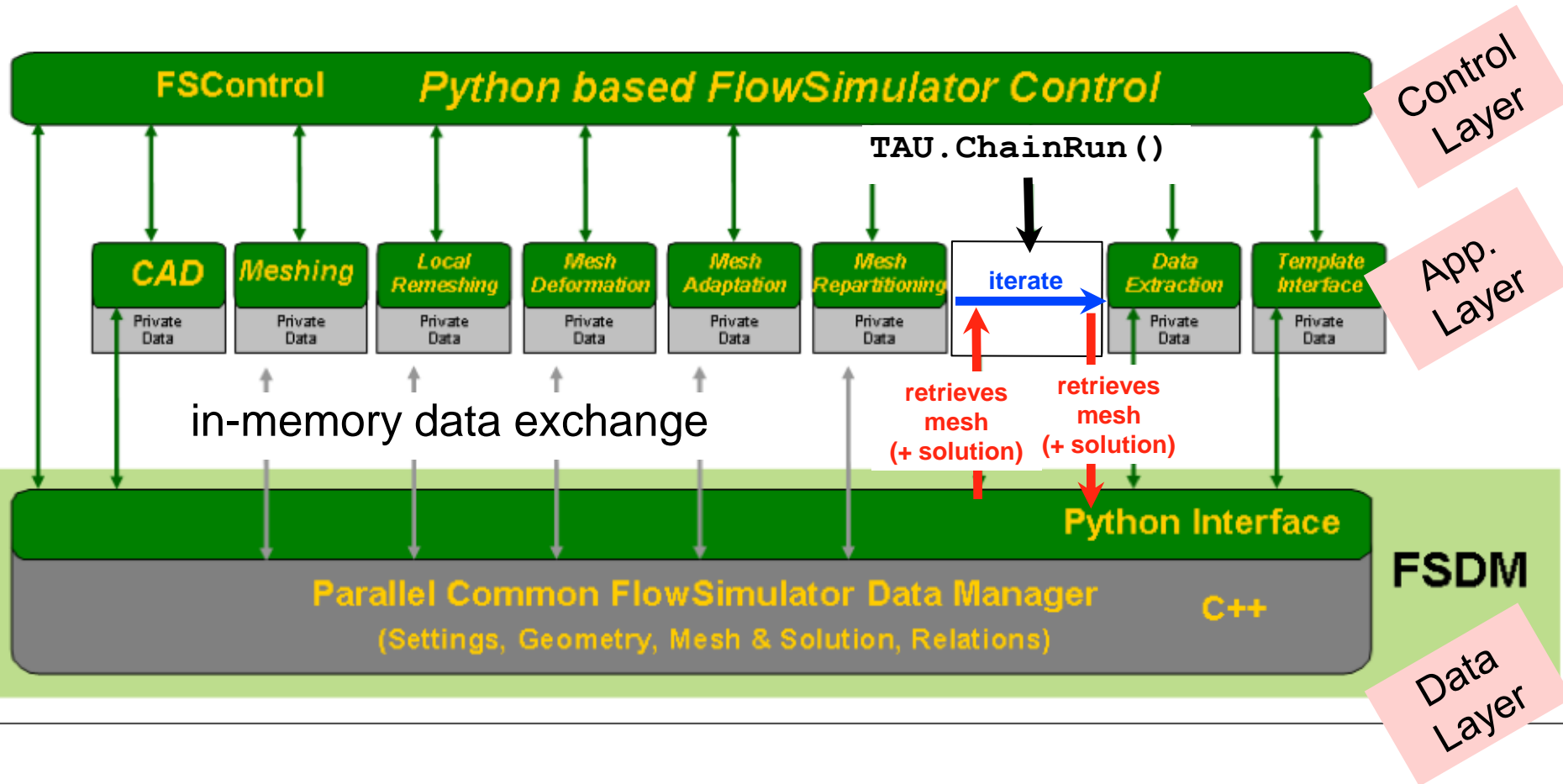
Vollständige Bezeichnung ↕	Accountname (Kleinbuchstaben) ↕	Beschreibung ↕
TAU Solver (FS-Mod)	fstau	TAU is a highly sophisticated unstructured CFD solver for compressible flows.
SELENE	selene	Computation of flight-over-noise and acoustic optimization of flight procedures of helicopters (EC135, BO105)
FSTrim	fstrim	Trim module of FlowSimulator
FSPrimgrid	fsprimgrid	This is the in-memory converter for TauPrimgrid and FSMesh.
FSNumPyInterface	fsnumpy	This module gives you a way to treat FSArrays in Python as NumPy arrays.
FSMeshConverter	fsmeshconvert	This plugin allows you to convert structured meshes to unstructured ones.
FSForce	fsforce	FSForce - generic friction and pressure coefficient integration for structured and unstructured meshes
FSExtraConnectivity	fsextraconn	A FSDM module that discovers extra connectivity information.
FSelsA	fselsa	A FlowSimulator plugin providing bindings to elsA.
FSEADM	fseadm	Provide EADM tool suite bindings for FlowSimulator.
FSDM Zoltan Partitionier Integration	fszoltan	This FSDM extension (aka MeshOp) integrates the Zoltan PHG hypergraph partitionier.
FSDM Support	fsdmsupport	This project bundles some small modules that are optional requirements for FlowSimulator DataManager.
FSDM CGNS-IO	fscansio	Extension of the Import/Export filter
FSDemoData	fsdemodata	Example data for use with FSDM.
FSDeformation	fsdeformation	Deformation module for FSDM
FSDamasIO	fsdamasio	DAMAS in-/output for FlowSimulator
FSCouple	fscouple	A generalized coupling framework
FSCatia interface	fscatia	Provides a tool to export CATIA geometry
fsbsurf	fsbsurf	A FlowSimulator module for BSurf P
FSAdvancedSplining	fsadvsplining	FlowSimulator-plugin dealing with s

- Join *FlowSimulator* projects of your interest
- Access developer releases
- Follow development process (commit mess.) & bugfixes



FS' Design Dogma for Replaceability of Sim. Components

- NO horizontal data exchange between simulation components



Trim Simulations with FlowSimulator



General Longitudinal Trim Process

Initial CFD solution

While trim condition **not** fulfilled
(here $C_L = C_{L,Target}$, $C_{My} = 0$):

If Jacobian is to be updated:

Computation of Jacobian:

- Perturbation of control variable (here AoA, HTP)
- Transfer perturbed control variable into BCs/mesh
- Compute CFD sol. for perturbed state

Compute Newton step (here for AoA & HTP)

Transfer altered control variable into BCs/mesh

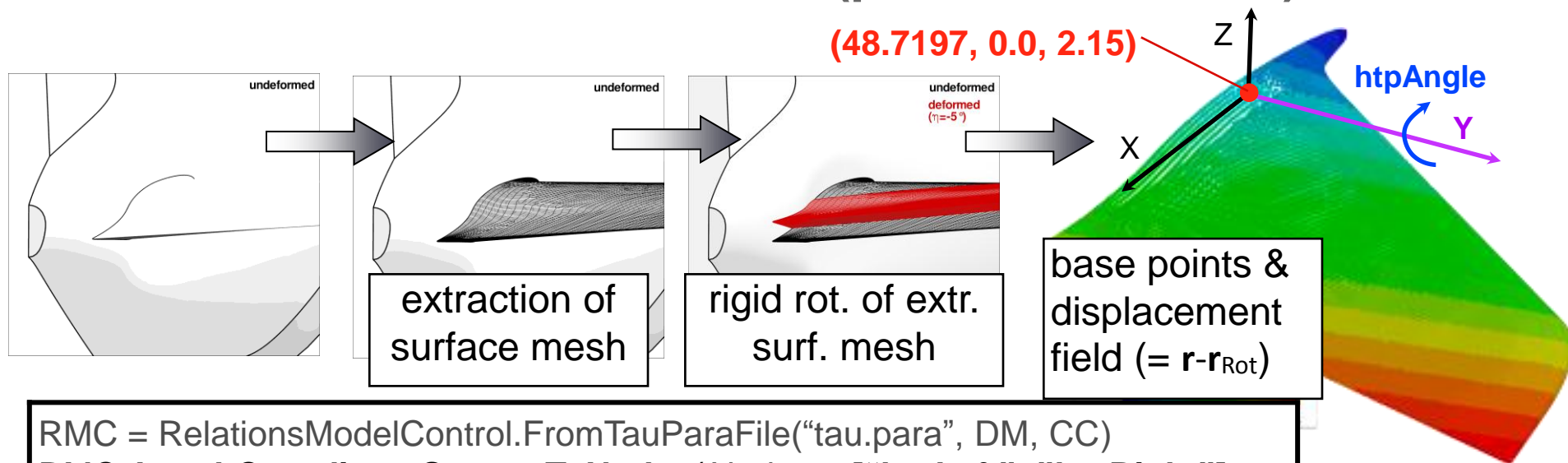
Compute CFD solution

LOOP

Challenge:
Rotation of HTP while preserving the fuselage geometry



Computation of the Scattered Displacement Field for the HTP Rotation: FS' MeshTools (part of FSControl)



```
RMC = RelationsModelControl.FromTauParaFile("tau para", DM, CC)
RMC.AttachCoordinateSystemToNodes( Nodes = ["htpLeft", "htpRight"],
                                     CommonNode = "HTP",
                                     Origin = [48.7197, 0.0, 2.15])
```

define rotation axis in relation model

```
MeshTools = MeshTools(DM, RMC)
```

```
basePoints, dispVecs = \
```

```
    MeshTools.GetDefoVectorsForRotation( MeshKey = "myMesh",
    ModelNodeName = "HTP",
    Axis = "Y",
    Angle = htpAngle)
```

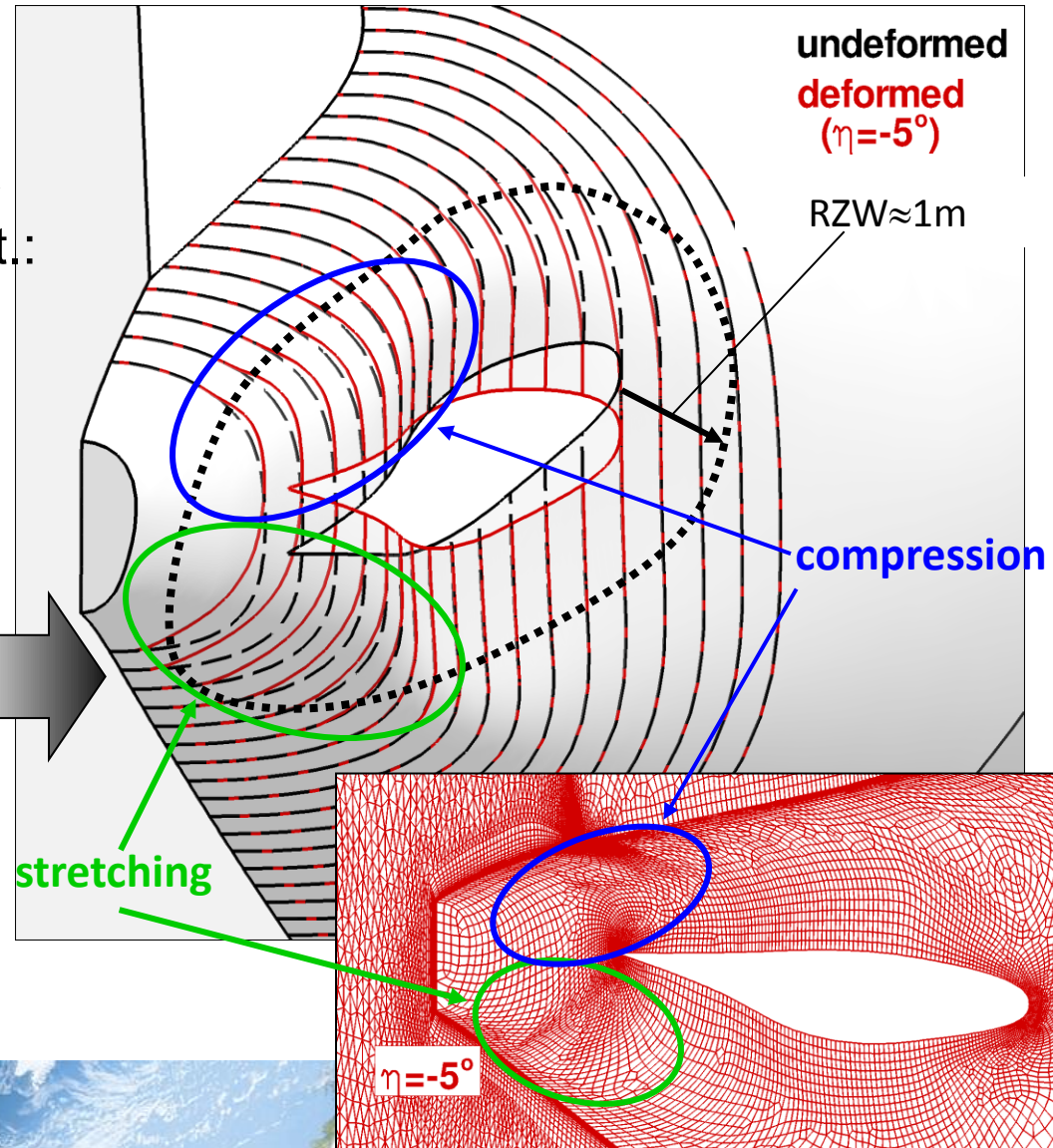
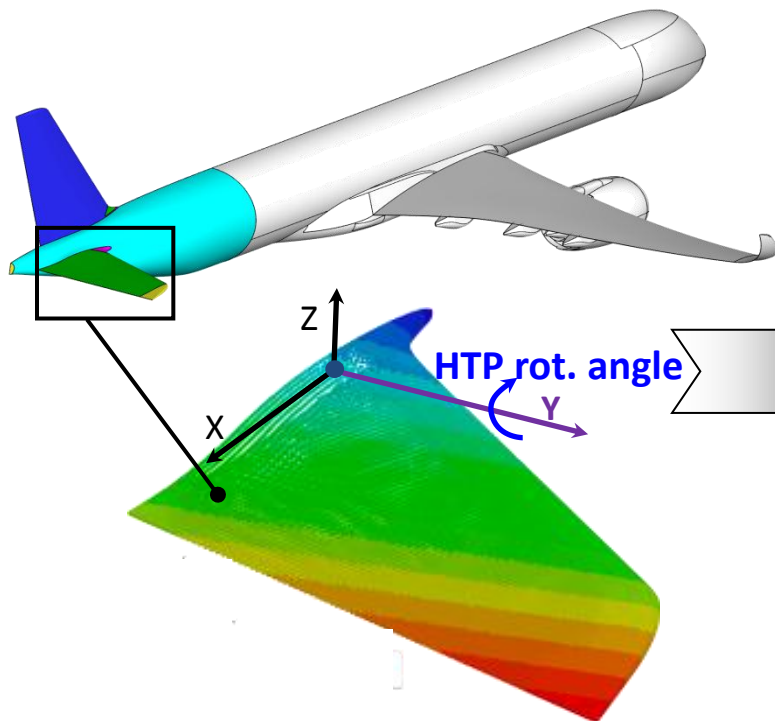
apply rotation & return displ. field



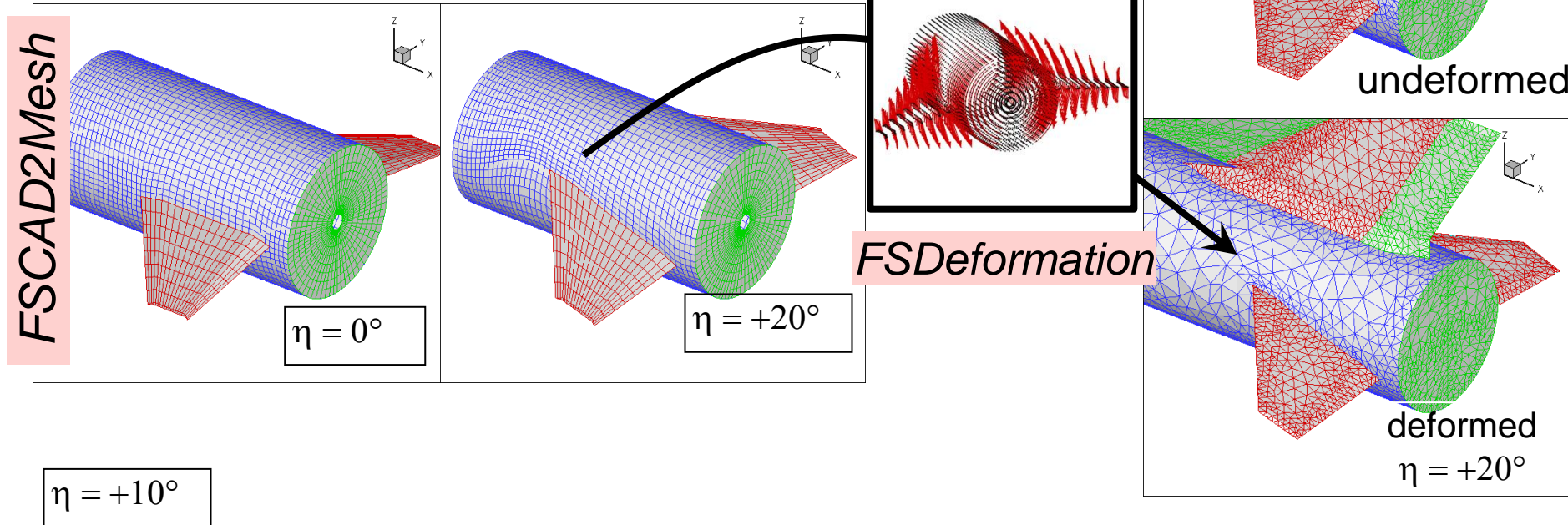
Problem with Mesh Deformation at HTP-Fuselage Intersection

Example A350-1000:

- HTP rot. in trim computations
- Prescribed displacement field corresponding to rigid HTP rot.:

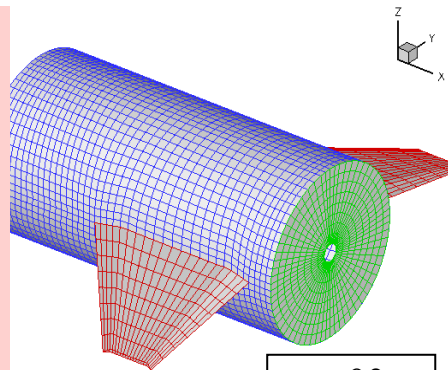


CAD-based Preparation of the Scattered Displacement Fields + Mesh Deformation: FSCAD2Mesh + FSDefoFields

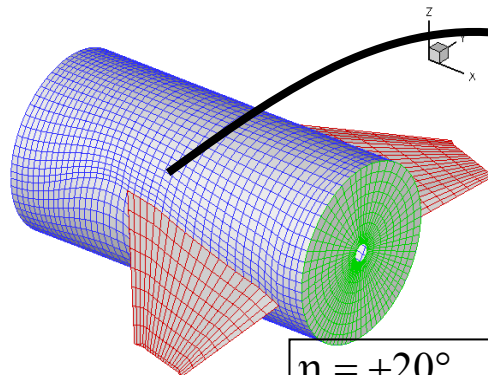


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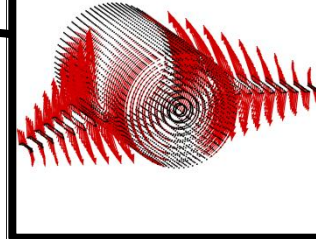
FSCAD2Mesh



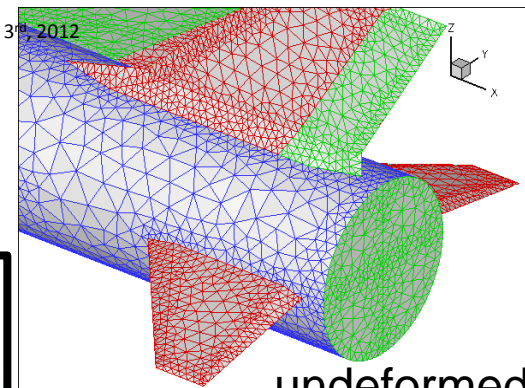
$\eta = 0^\circ$



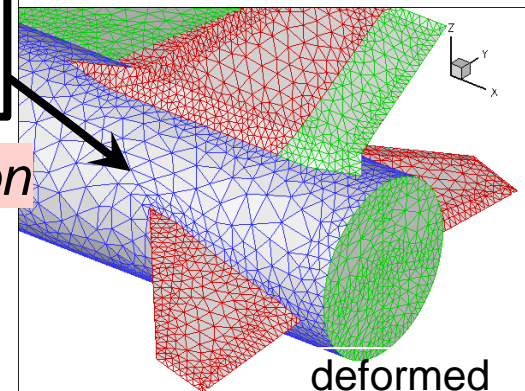
$\eta = +20^\circ$



FSDeformation



undeformed

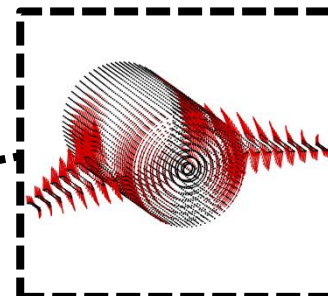
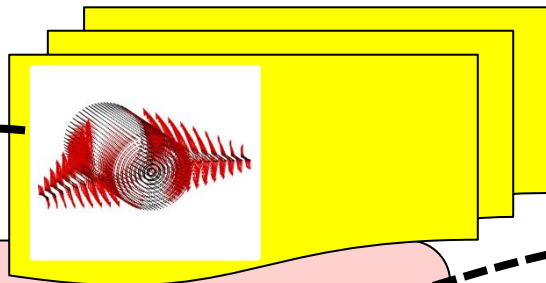


deformed
 $\eta = +20^\circ$

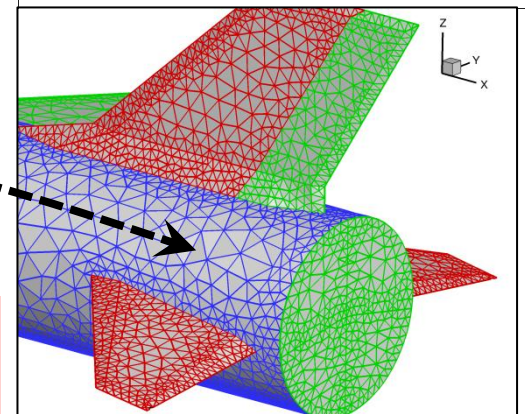
$\eta = +10^\circ$

?

FSDeformation

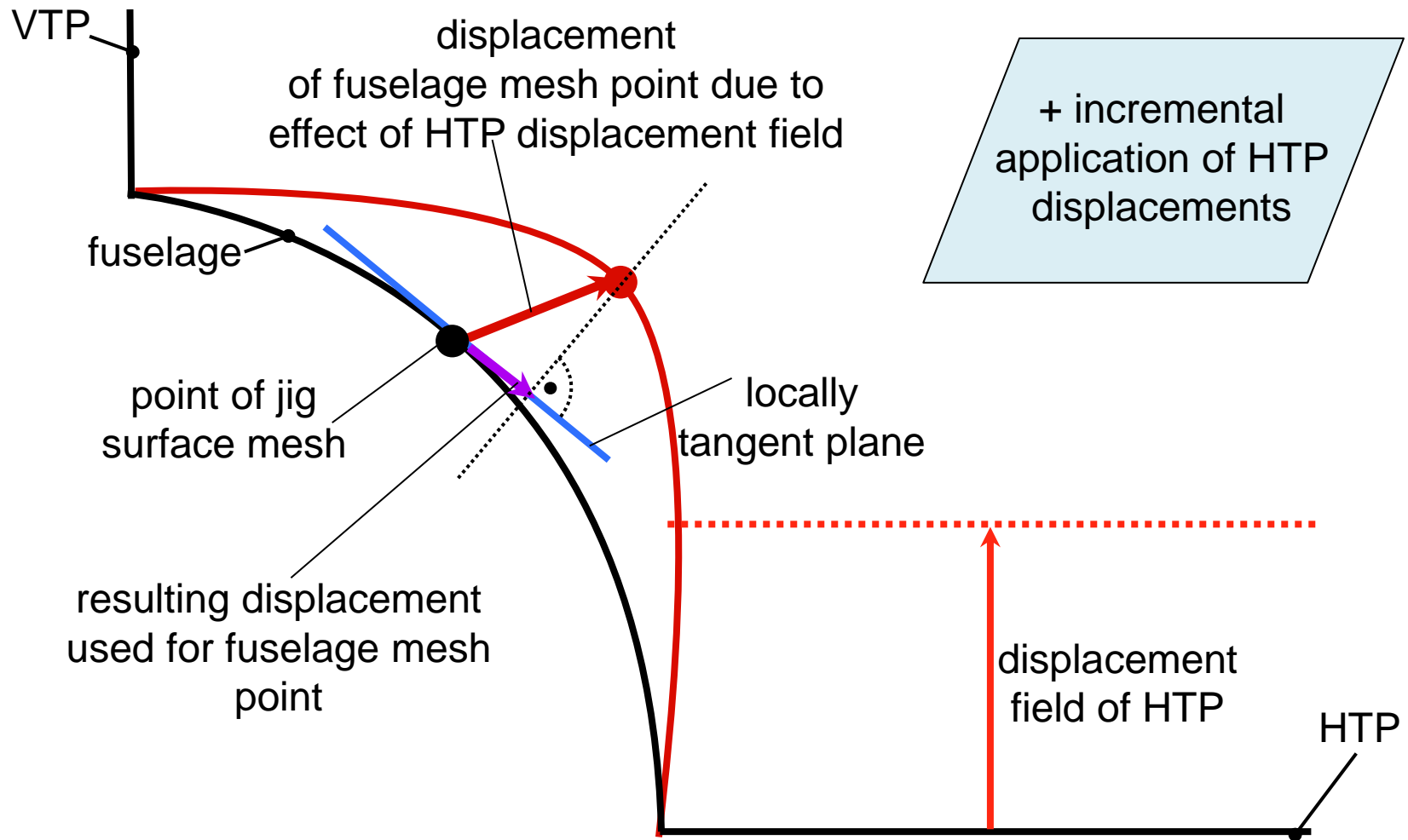


Interpolation of
scattered displ. field
+ FSDeformation



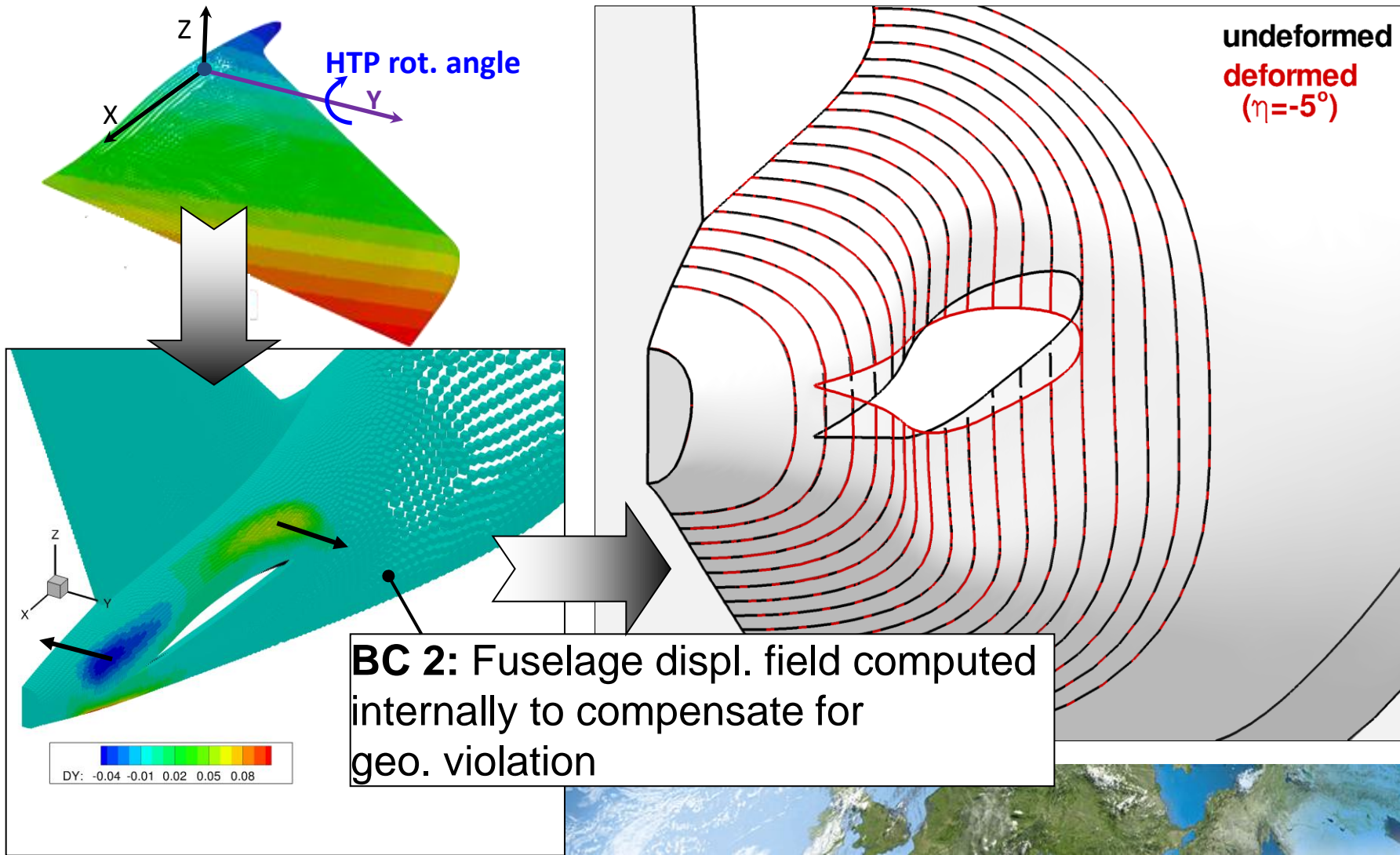
deformed
 $\eta = +10^\circ$

Other Strategy: Special “No-Normal-Movement” BC of FSDeformation



Use of FSDeformations' No-Normal-Movement BC for Fuselage when Rotating HTPc

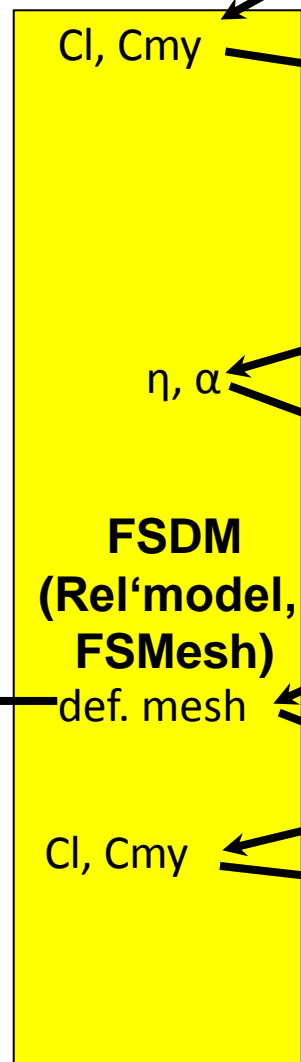
BC 1: Displacement field for rigidly rotated HTP



Trim Loop Implemented in FlowSimulator

Required Input data:

- Boundary marker of HTP
- Boundary marker of attached fuselage part
- HTP rotation axis (origin, direction)
- Initial HTP setting η
- Initial α
- Target lift, pitch (trimmed state = 0)



Initial TAU run: TAU.ChainRun()

FSTrim.ImportFromFSDM

While trim condition not fulfilled:

FSTrim computes perturbation

FSTrim.ExportToFSDM

FSMeshTools: Compute displacement field representing rigid HTP rot.

$\mathbf{x}, \Delta \mathbf{x}$

FSDeformation.ChainRun

Run TAU

FSTrim.ImportFromFSDM

FSTrim: evaluation of trim condition

Final TAU run for trimmed state

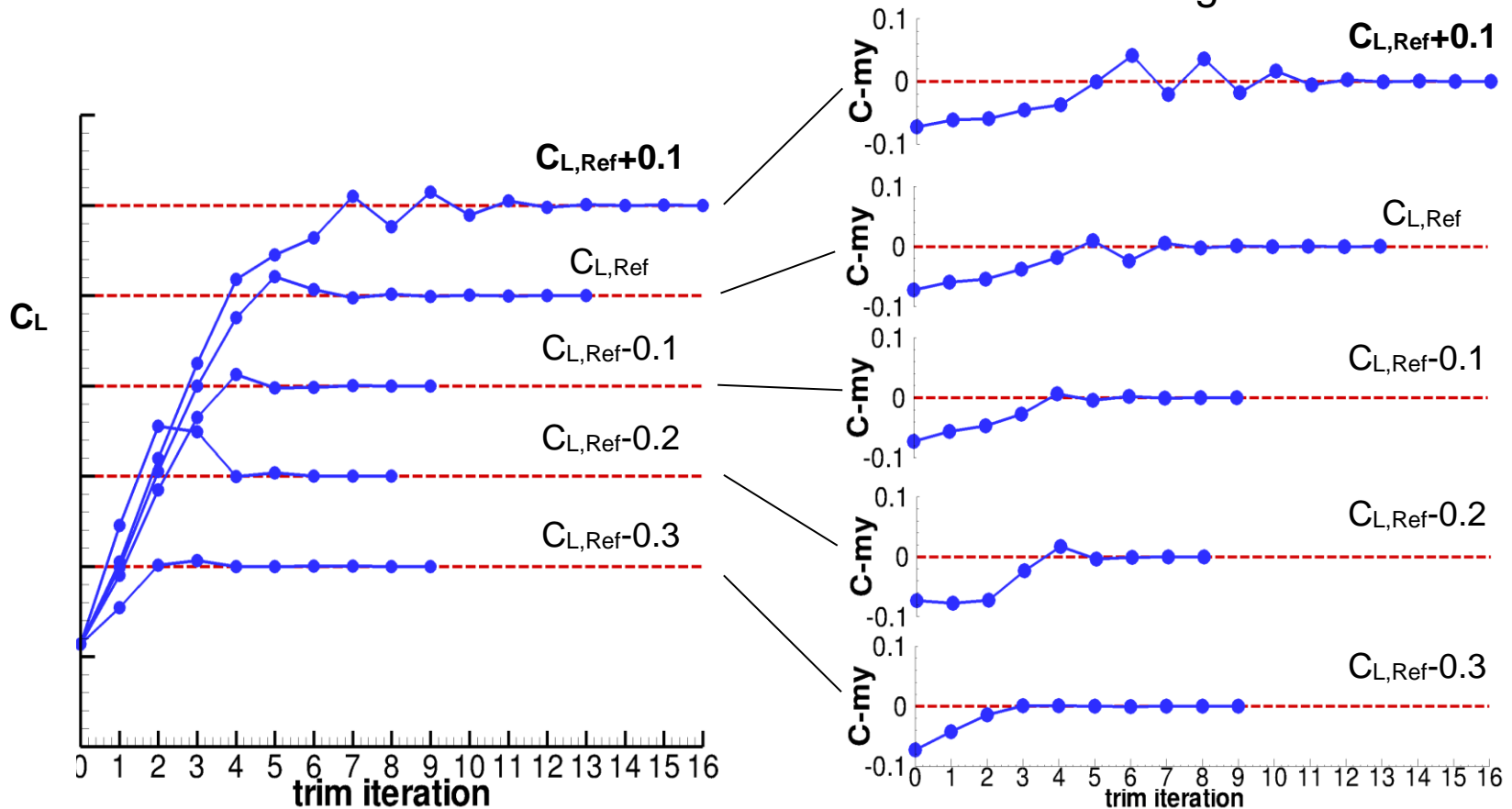
LOOP

Use Case “Longitudinal Trim”

- FSTau-based simulations
- All computations started from free-stream conditions
- $AoA_{ini}=0^\circ$, $HTP_{ini}=0^\circ$, i.e. untrimmed
- Thrust not considered yet in equation of moments



A350-1000 test case:
SOLAR mesh, 18m pts.,
engine BC

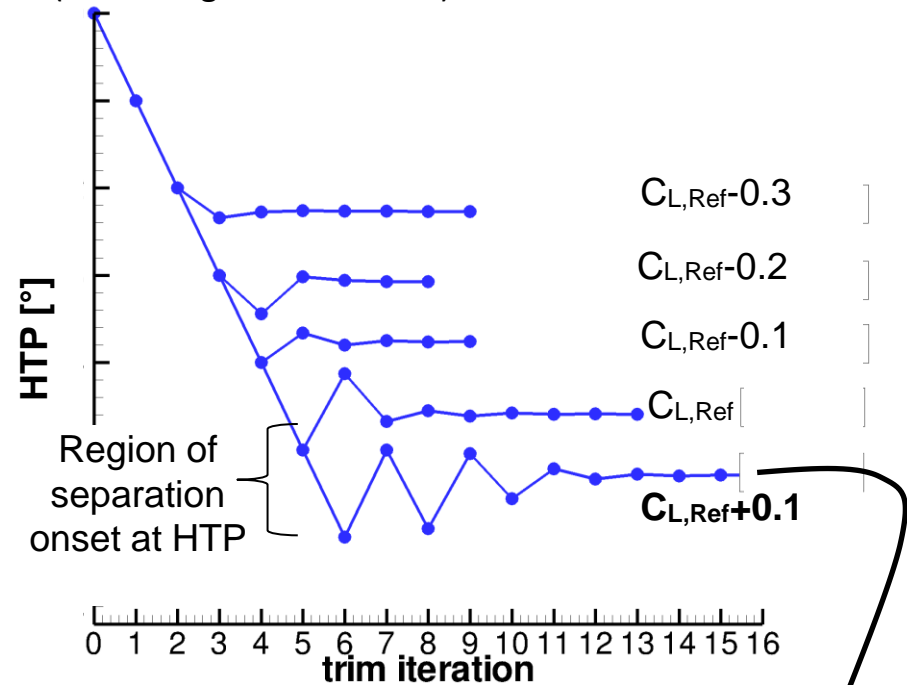
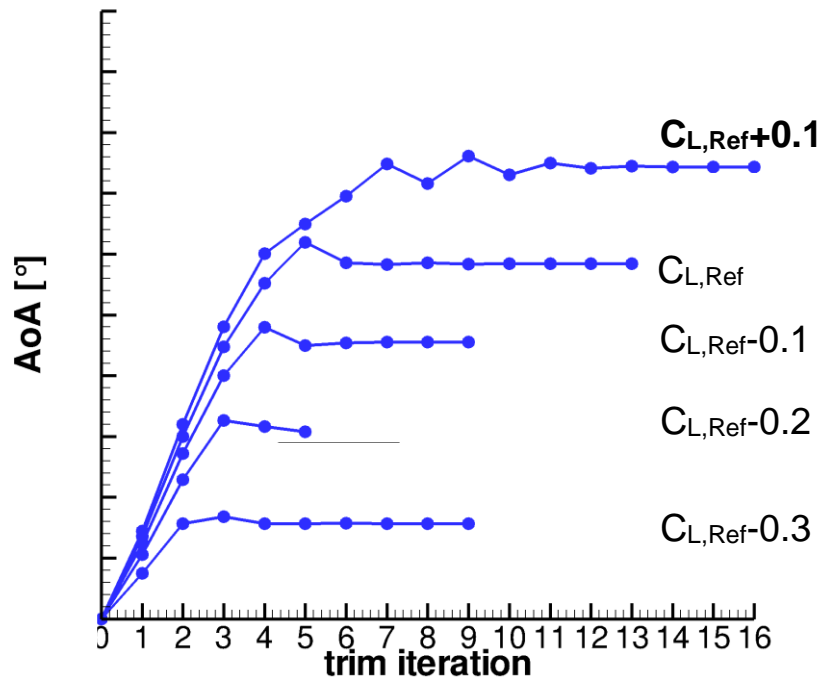


Use Case “Longitudinal Trim”

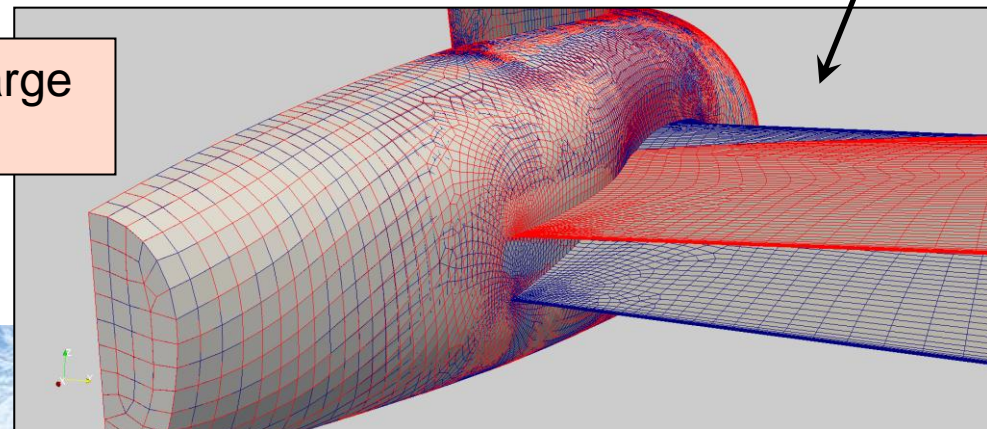
A350-1000
test case



Remark: HTP 0° indicates the initial setting of the HTP in the CFD mesh (which might be non-zero)



Fuselage shape retained, even for large HTP rotation angles (+1° to -10°)



A350-1000
test case

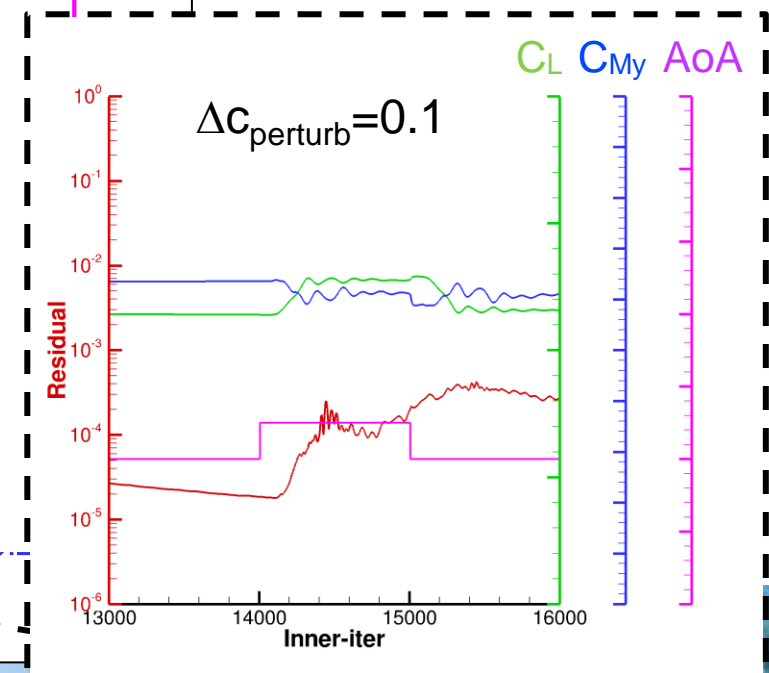
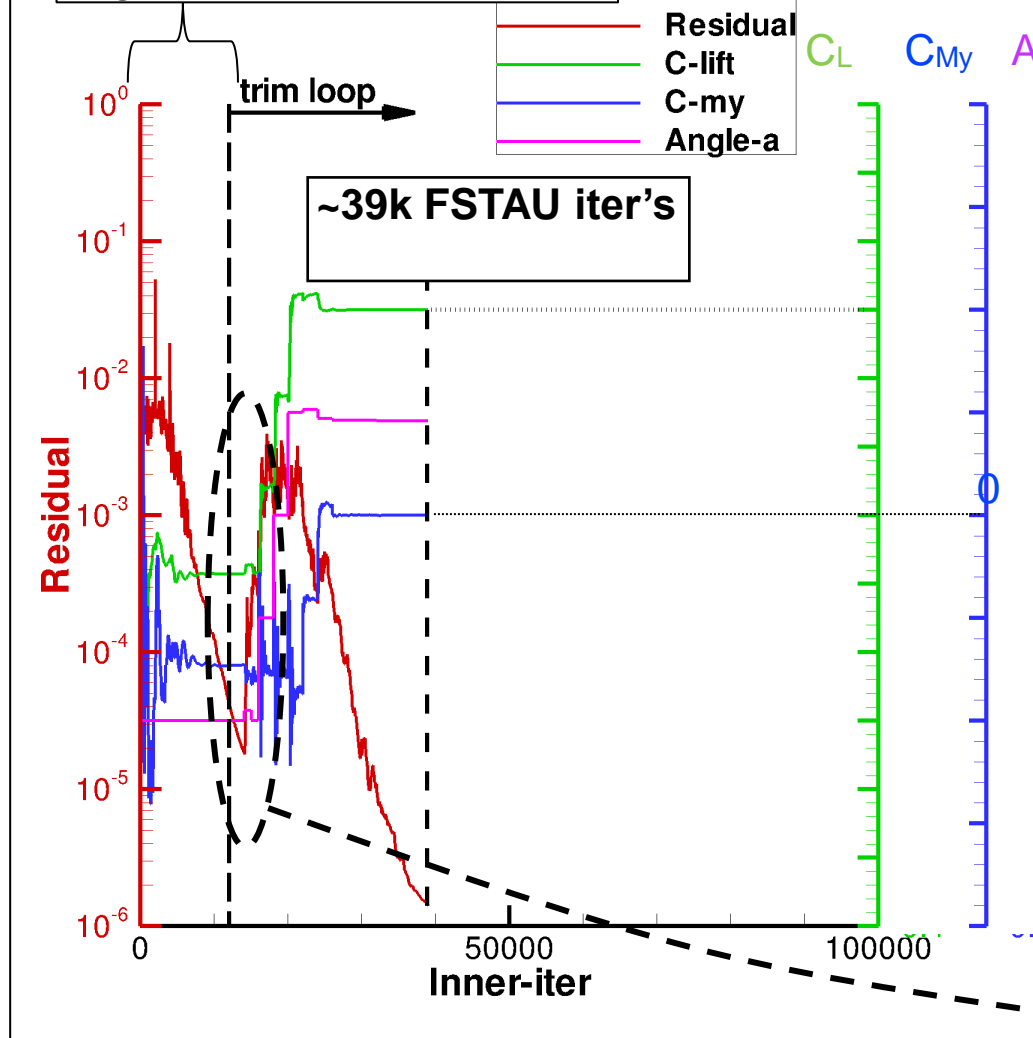
Use Case “Longitudinal Trim”

Ini. CFD iter's. incl.
engine start-up procedure

Jacobian computed only
once by forw. difference:

$$J = \begin{pmatrix} dCL/d\alpha & dCM_y/d\alpha \\ dCL/d\eta & dCM_y/d\eta \end{pmatrix}$$

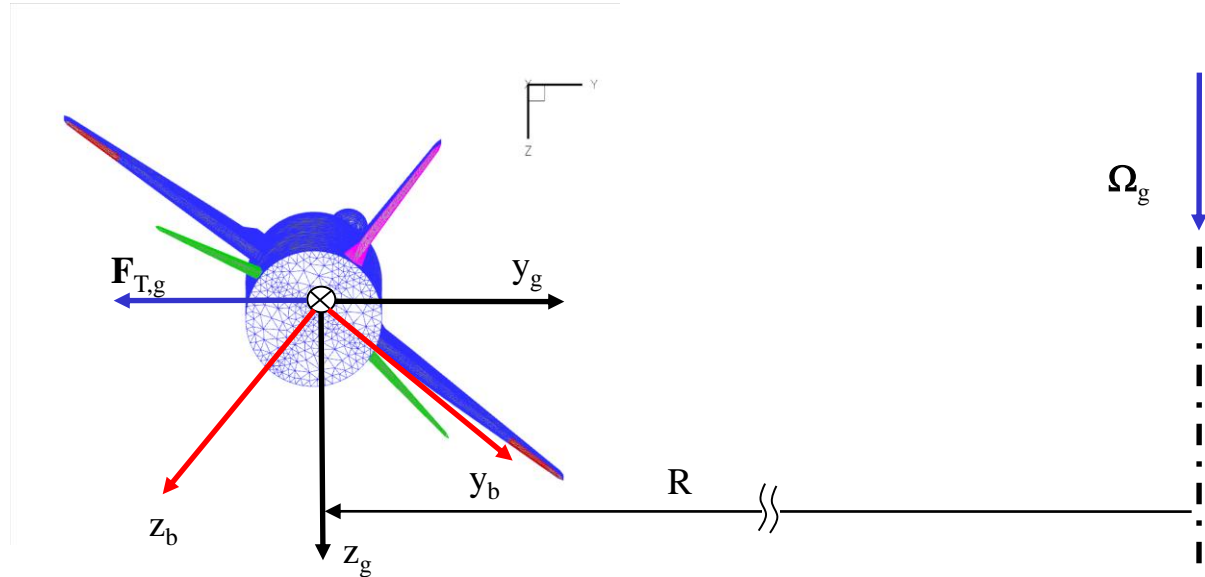
- 1 AoA perturbation
- 1 HTP perturbation



Use Case “Steady Curve Flight”: Simpler Config., but more Complex Trim Scenario

Involved FS Tools: FSTau + FSTrim + FSDeformation

$$F_{T,g} = m \frac{V_g^2}{R}$$



- We assume that the aircraft is flying a horizontal curve with radius 5000m with constant turn rate (angular velocity Ω_g).
- Flow parameters
 - $Ma_\infty = 0.5$, $p_\infty = 101325 \text{ N / m}^2$, $\rho_\infty = 1.29 \text{ kg / m}^3$, mass: 9295.44 kg



Use Case “Steady Curve Flight”

➤ Trim-condition / goal function used

Aerodynamic forces and moments

Thrust

Centrifugal force

$$0 = F_{x,aero,g} + T_{x,g}$$

$$0 = F_{y,aero,g} + T_{y,g} - m \frac{V_g^2}{R}$$

Gravity force

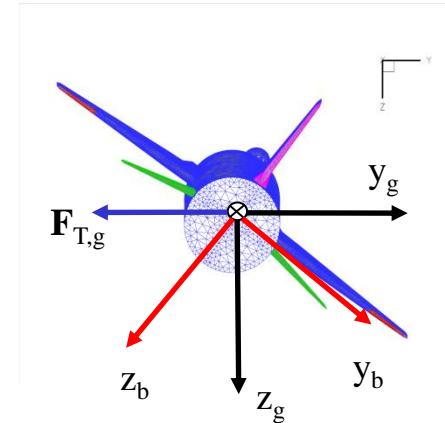
$$0 = F_{z,aero,g} + T_{z,g} + m g$$

$$0 = M_{x,aero,b} - (I_2 - I_3) q_b r_b$$

$$0 = M_{y,aero,b} - (I_3 - I_1) r_b p_b$$

$$0 = M_{z,aero,b} - (I_2 - I_3) p_b q_b$$

↑
Rate of change of angular momentum



➤ Control parameters :

Roll angle ϕ

Pitch angle Θ

Thrust

$\eta_{arileron}$

η_{rudder}

η_{HTP}

Initial values:

$=0^\circ$

$=5^\circ$

$=0 \text{ N}$

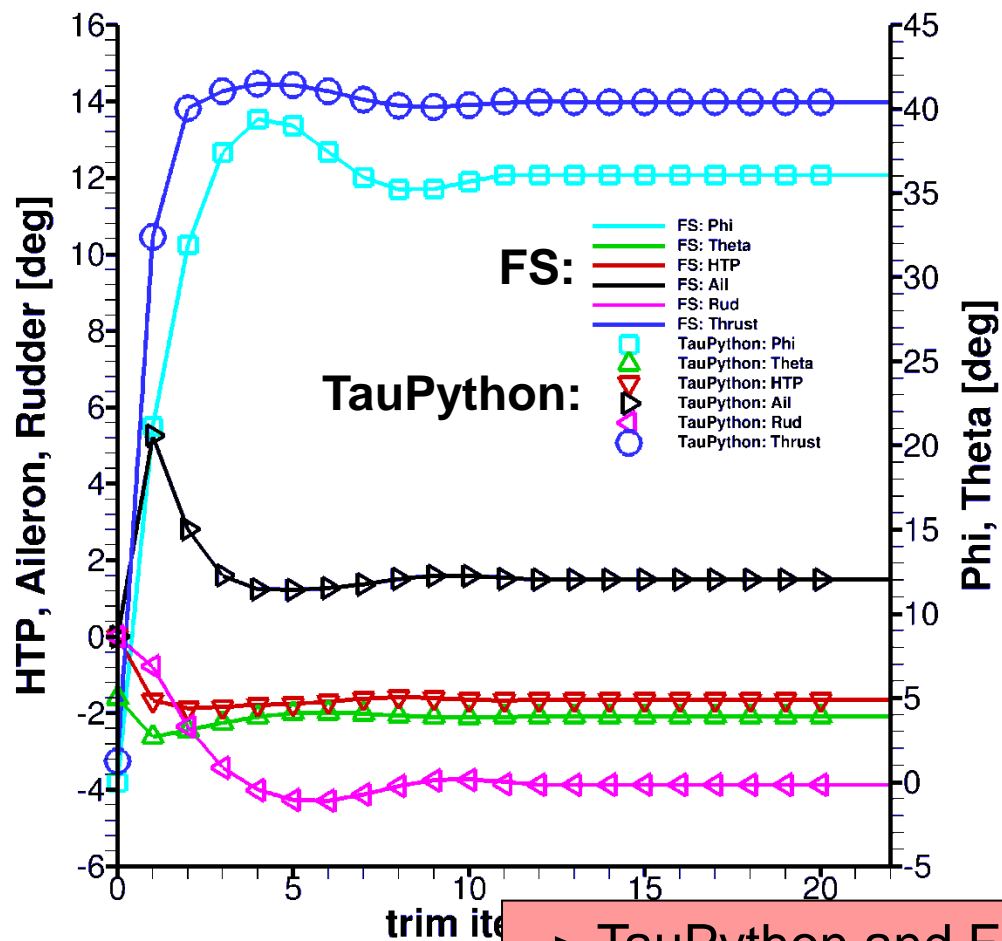
$=0^\circ$

$=0^\circ$

$=0^\circ$

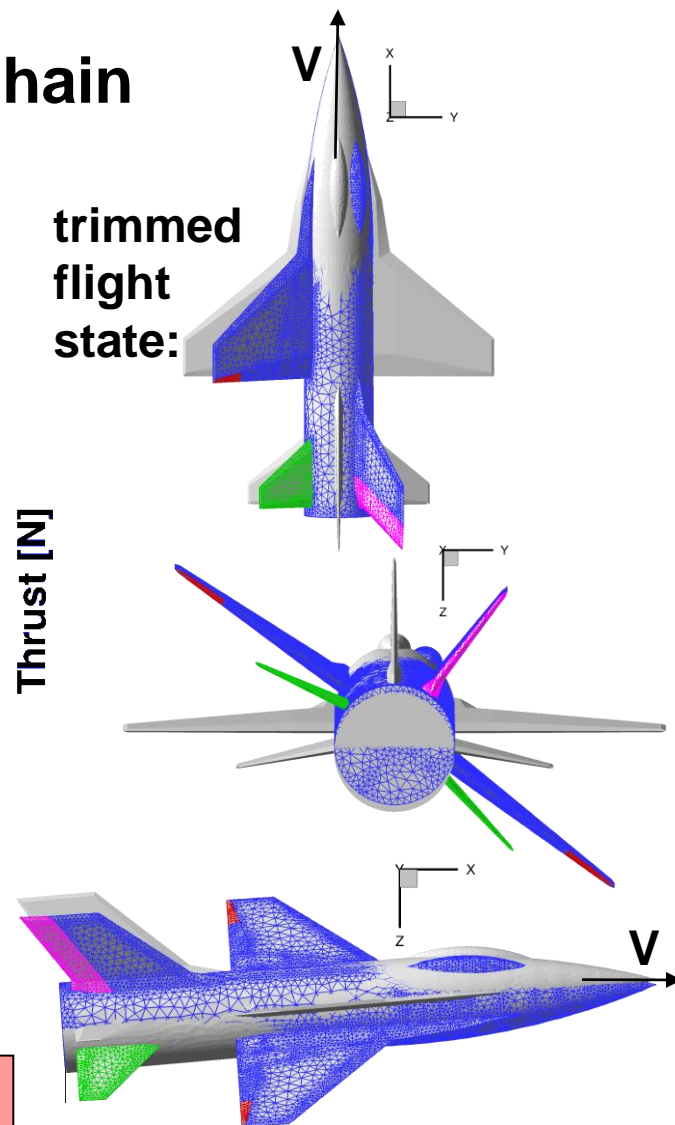


Use Case “Steady Curve Flight”: Comparison with TauPython Tool Chain



=> TauPython and FS
trim procedures yield
identical trim results

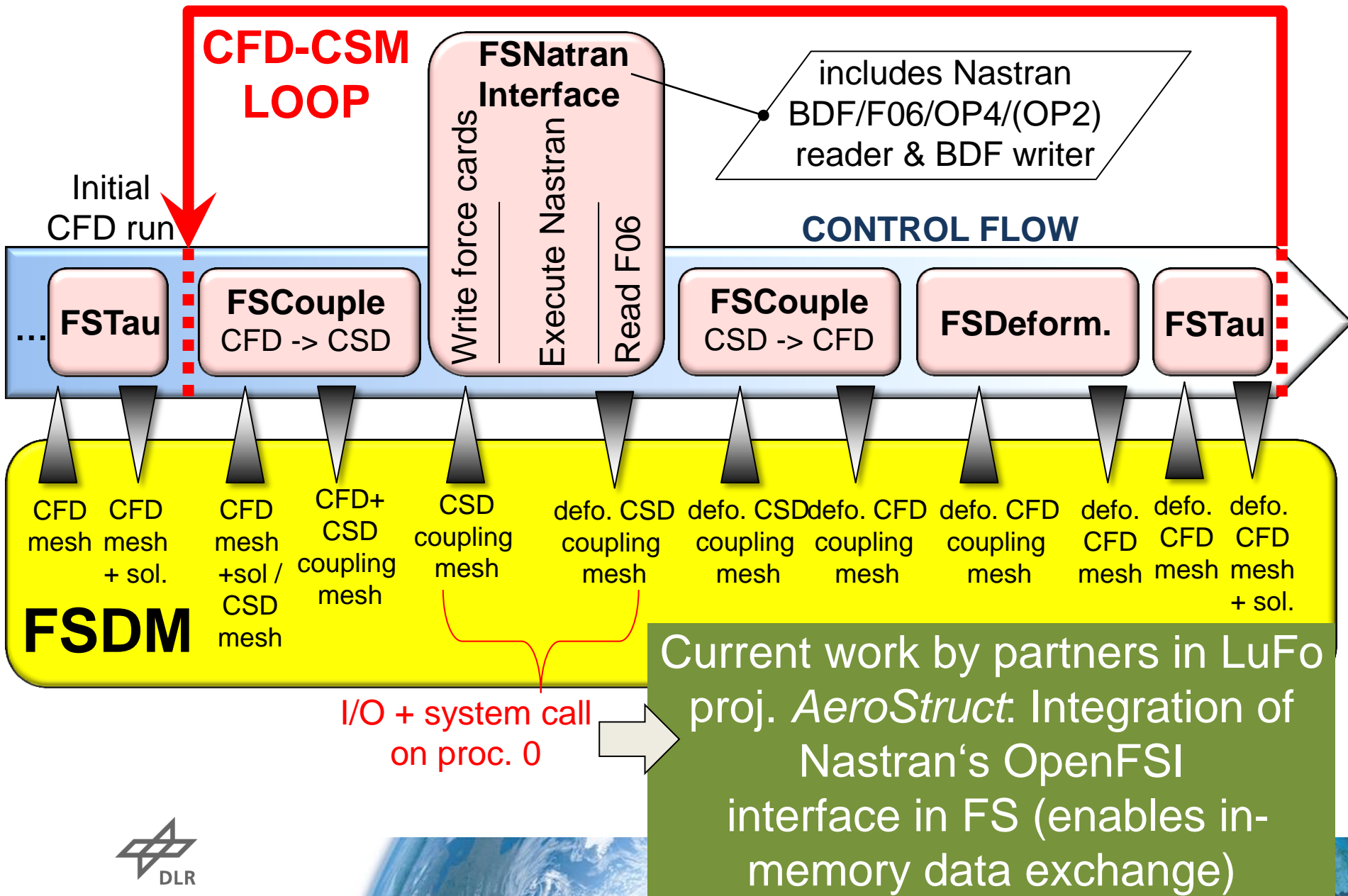
trimmed
flight
state:



CFD-CSD Coupled Simulations with FlowSimulator

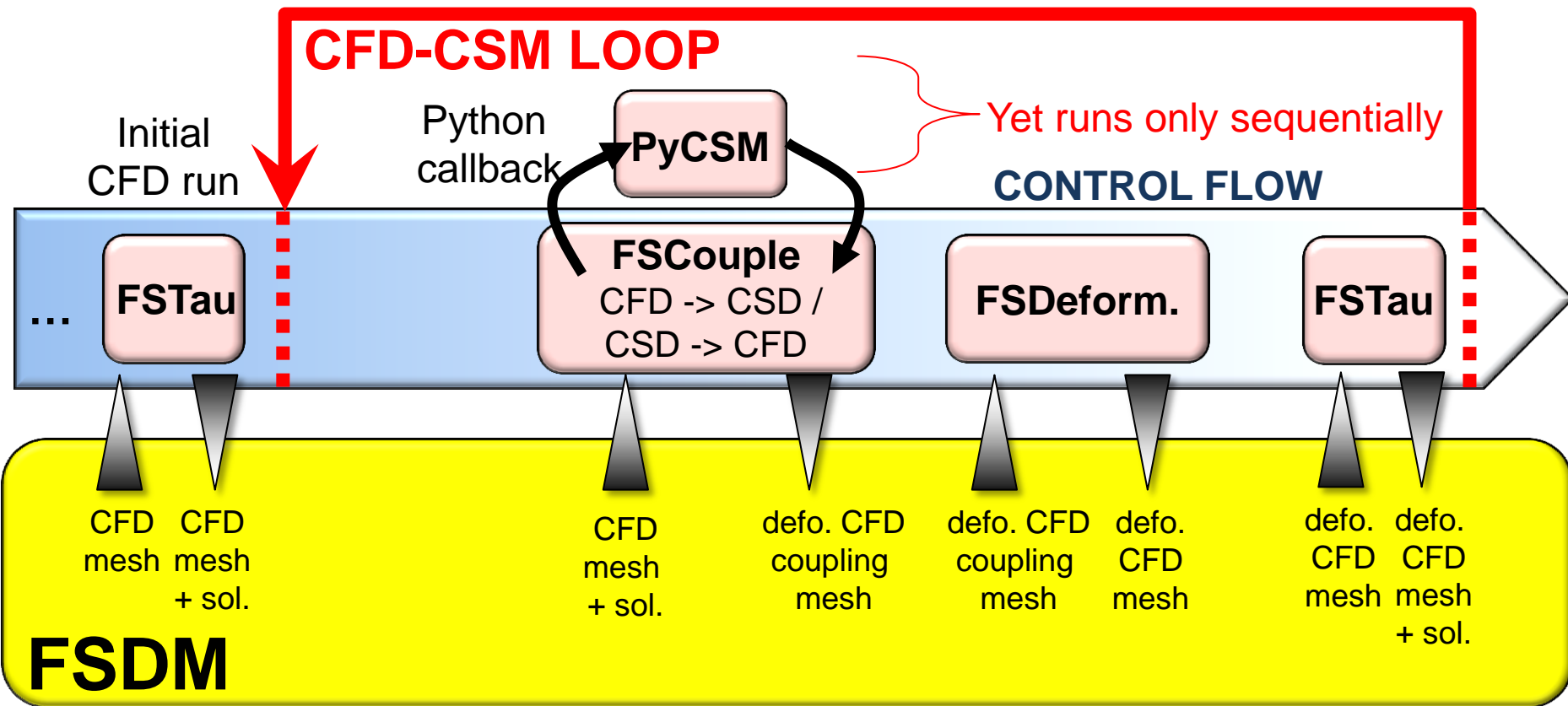
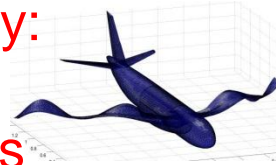


Nastran-based CFD-CSD Coupling with FS



PyCSM*-based CFD-CSD Coupling with FS

- * Python-based modal solver developed by DLR Institute of Aeroelasticity:
Includes modal solver +
CFD-CSD interpolation methods



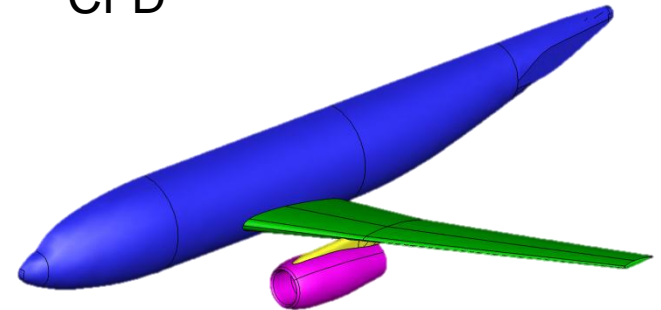
FSCouple

- Originated as a Cassidian development
- Regarded as central component for DLR's CFD-CSD coupling chains

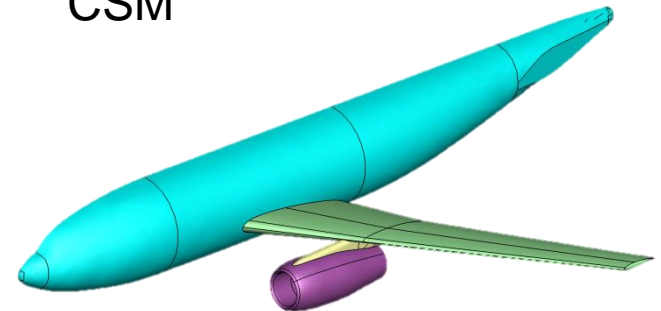
Features of FSCouple:

- Definition of pairings
(use of FSMeshSelection)

CFD



CSM

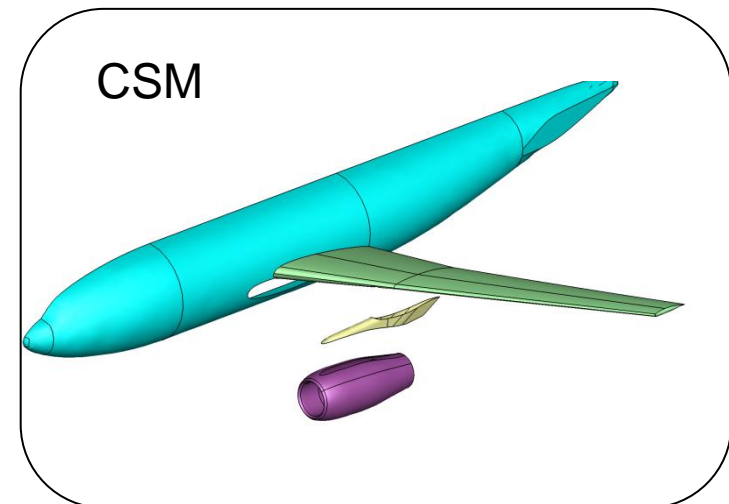
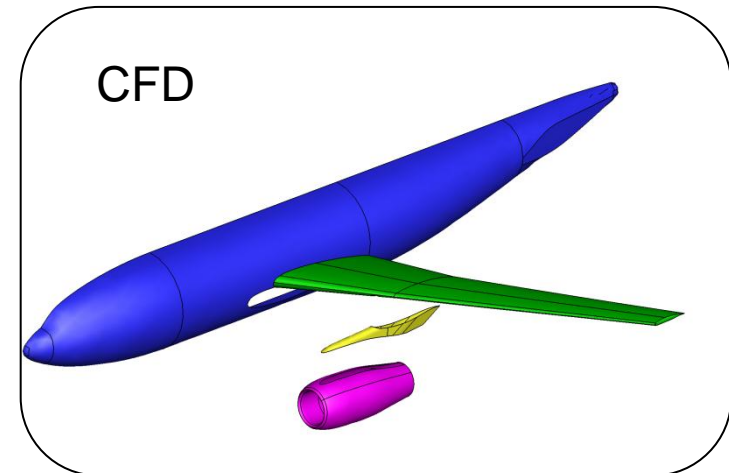


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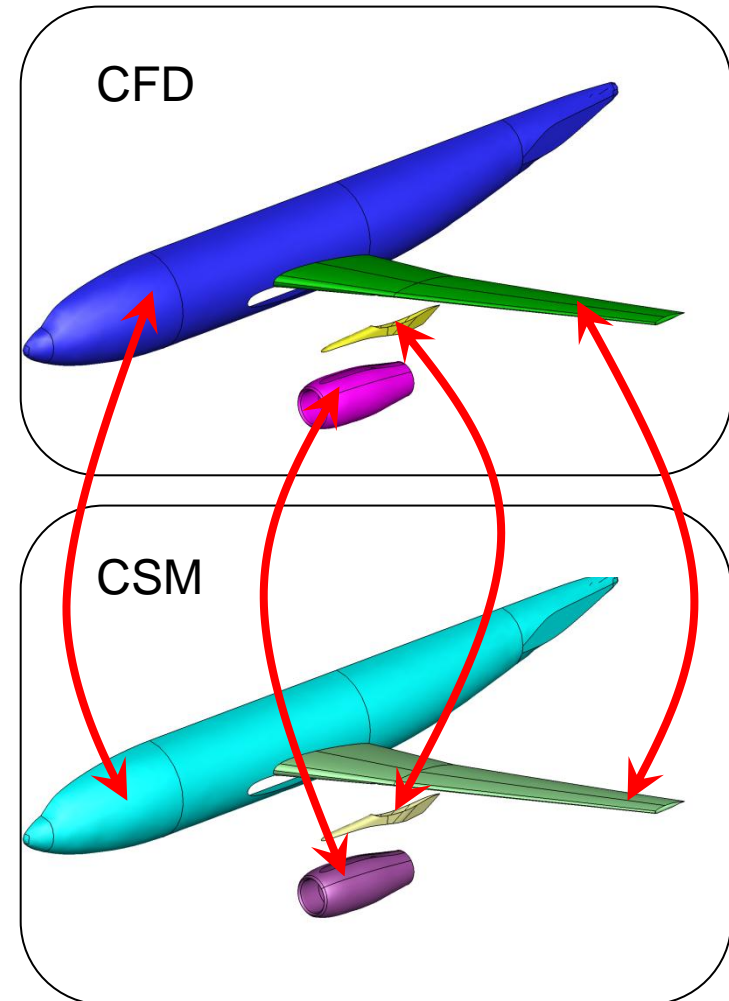


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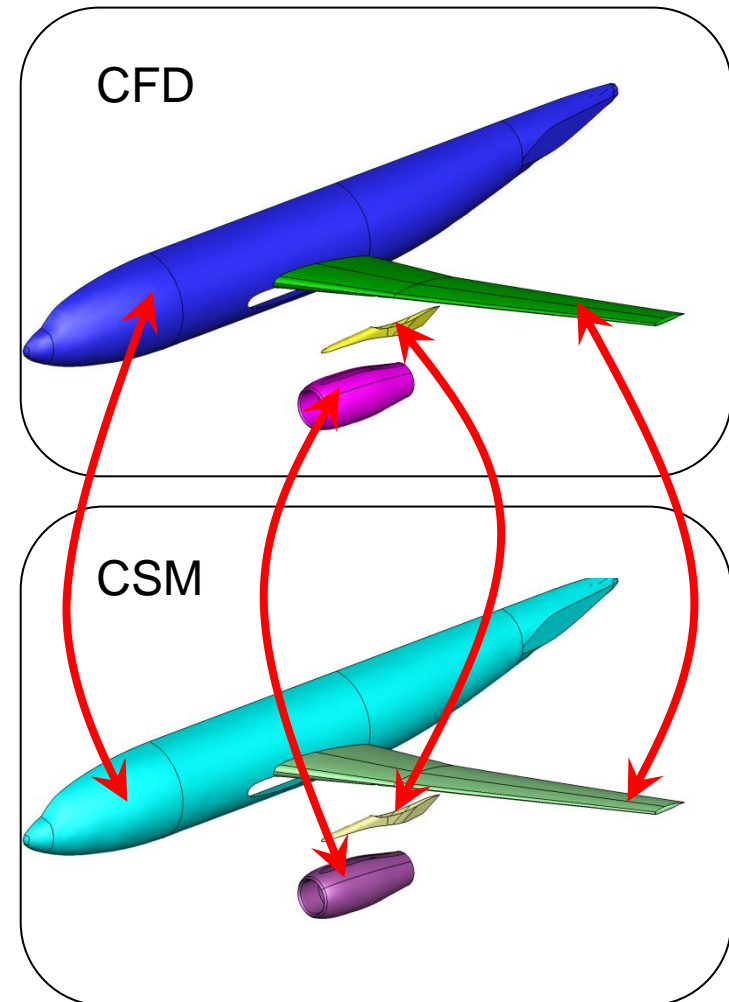


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Features of FSCouple:

- Definition of pairings (use of FSMeshSelection)
- Parallel handling of coupling meshes, e.g. repartitioning for improved load balance during interpolation
- Provides interface to interpolation methods (native FSDM methods: FSMeshInterpolation; other external methods via Python callback)



FSCouple

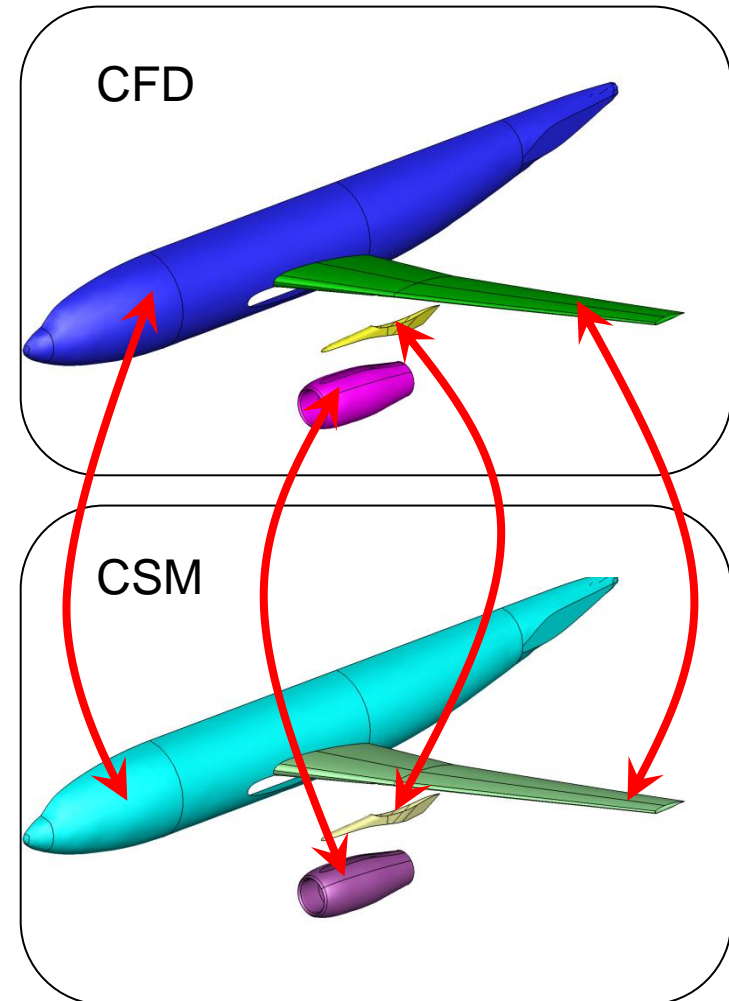
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Yet Missing Features:

Inter-pairing blending techniques
(planned to be implemented)



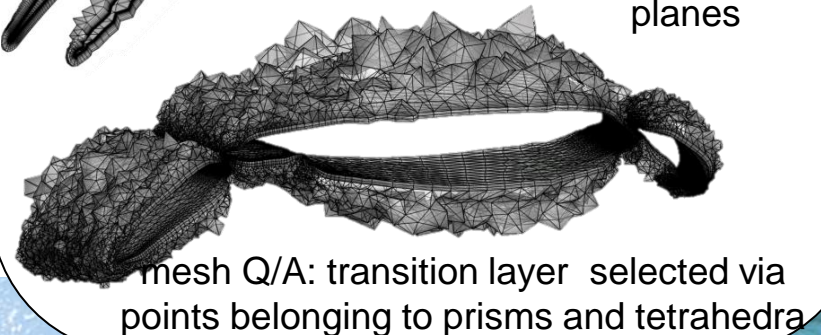
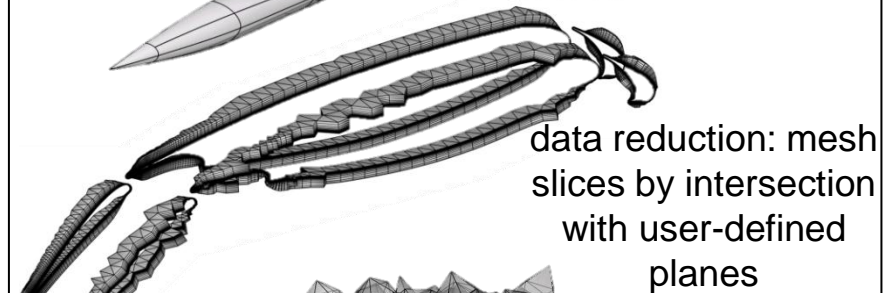
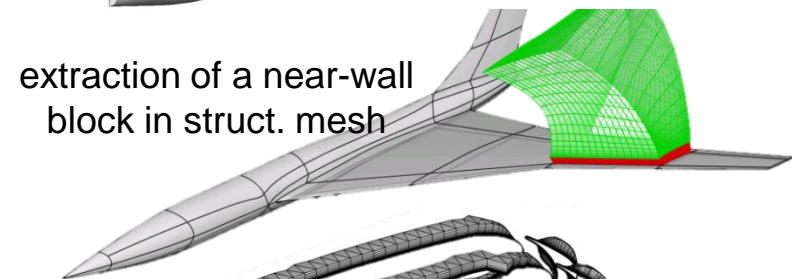
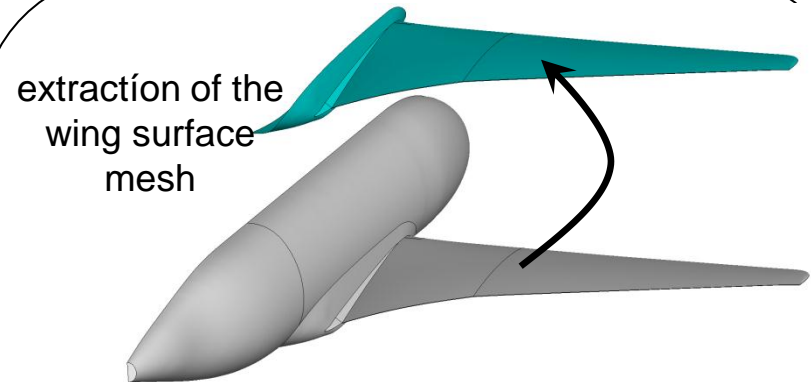
FSMeshSelection*

- Efficient in parallel mesh extraction tool
- Applicable to **structured** & **unstructured** meshes
- Allows intuitive boolean operations
- Mandatory to have for CFD-CSD coupling
- Nice to have for data reduction



*part of FSDM (=open source)

Example Applications



FSMeshInterpolation*: Interpolation of Pressure Distrib.

LANN case, FSTAU, $M=0.82$, $Re=7.3m$,
 $AoA=2.6^\circ$, SAO, 1.7m SOLAR mesh, 8 procs

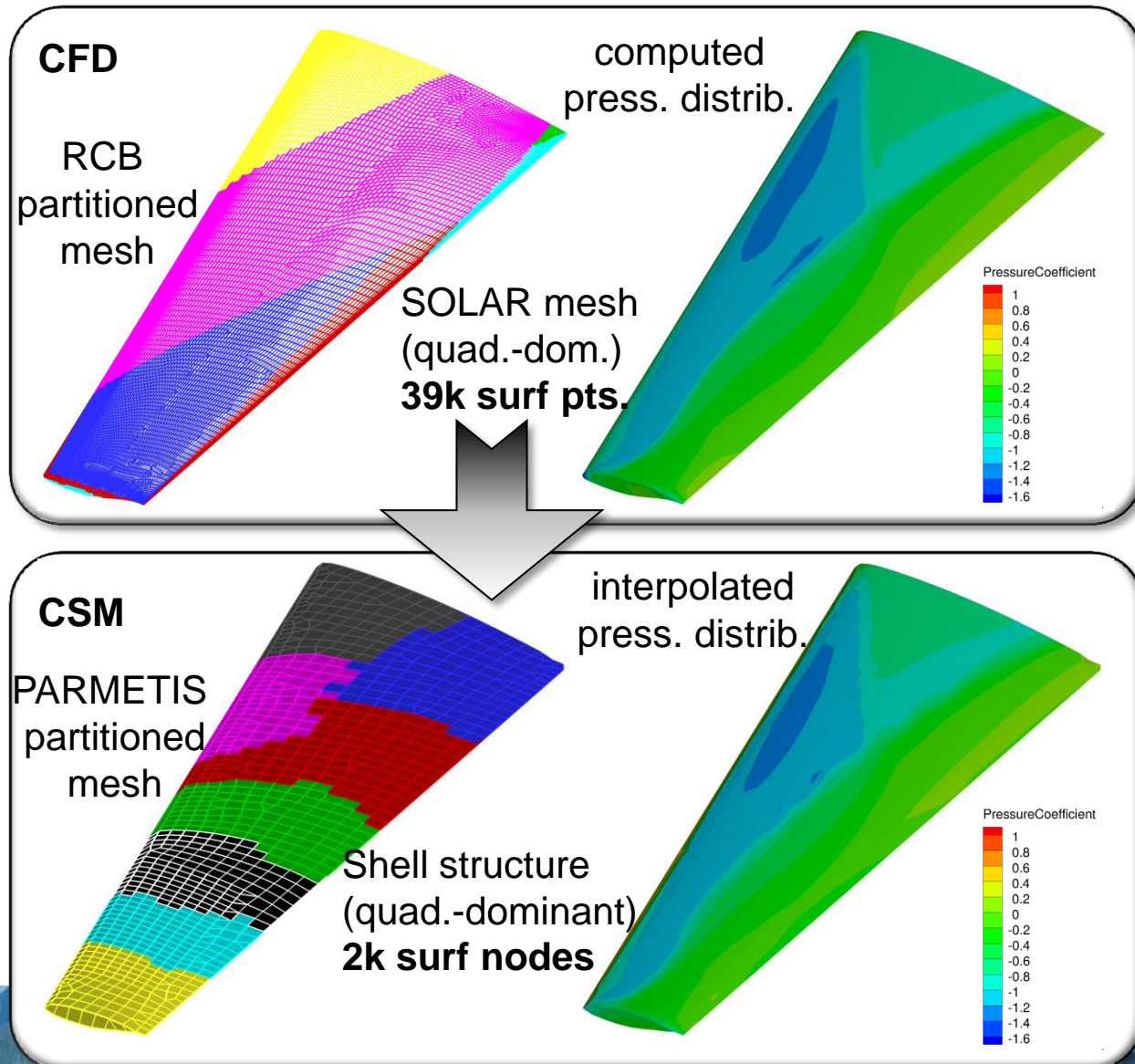
So far available meth's:

- Volume & surface mesh interpolation
- Nearest neighbour interpolation
- Iso-parametric mapping (FE shape func.)

Planned:

- RBF-based (MLS-type)

*part of FSDM (=open source)



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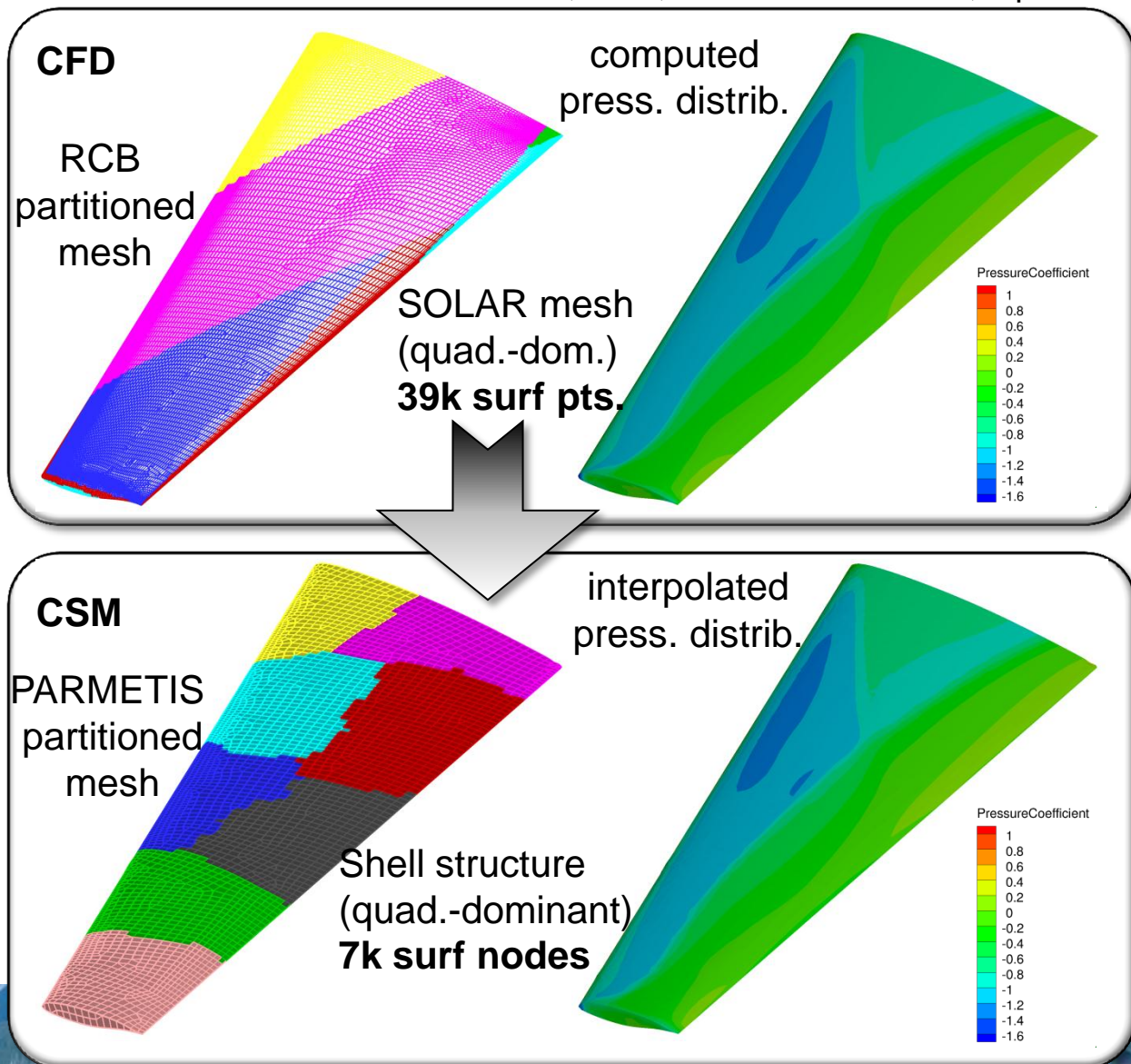
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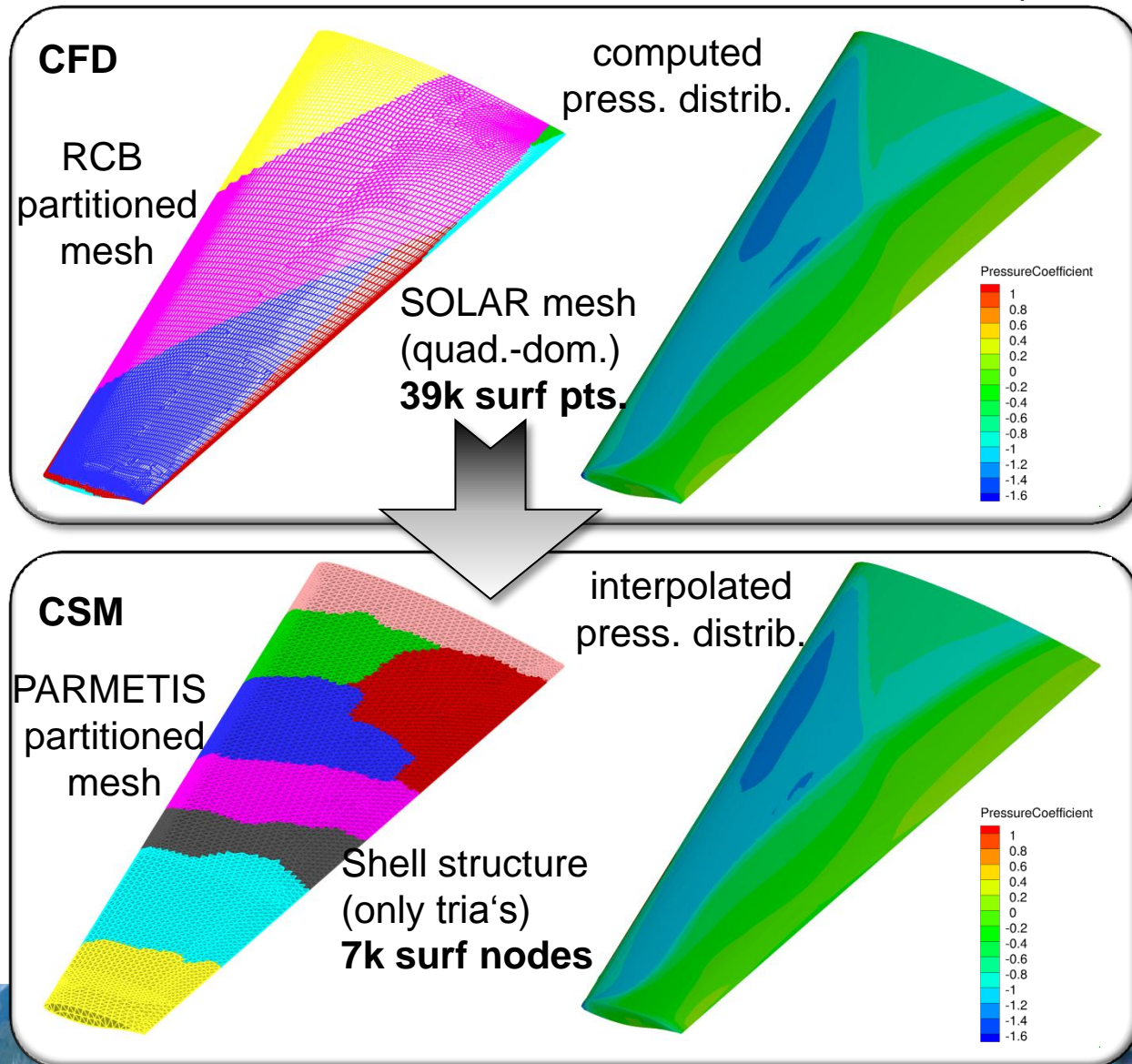
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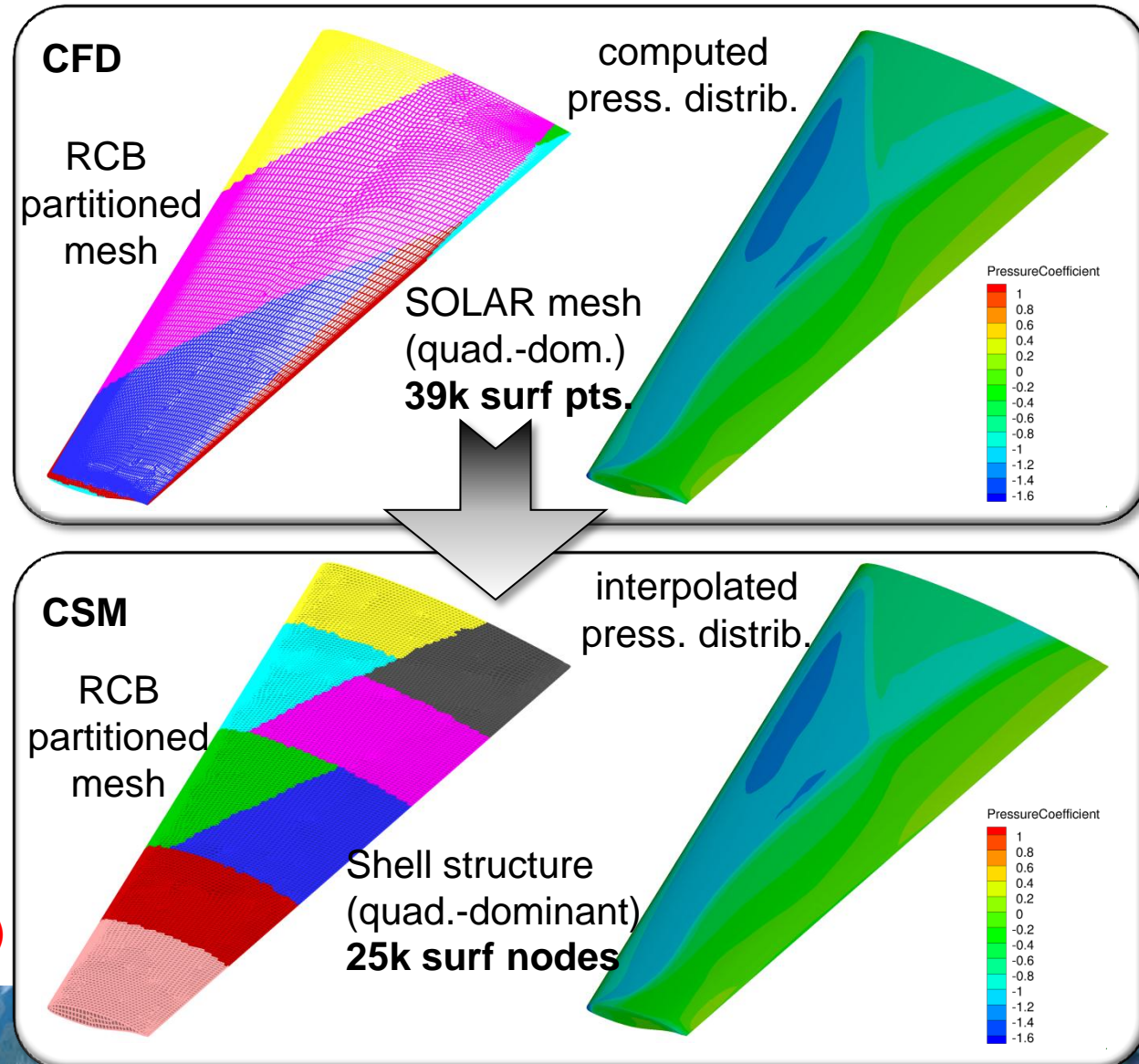
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FSMeshInterpolation*: Interpolation of Displacements

So far available meth's:

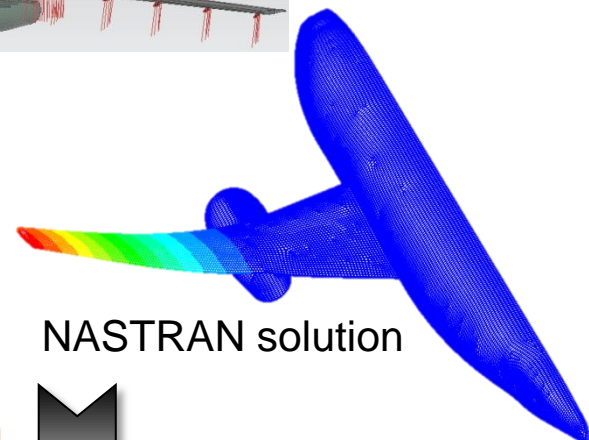
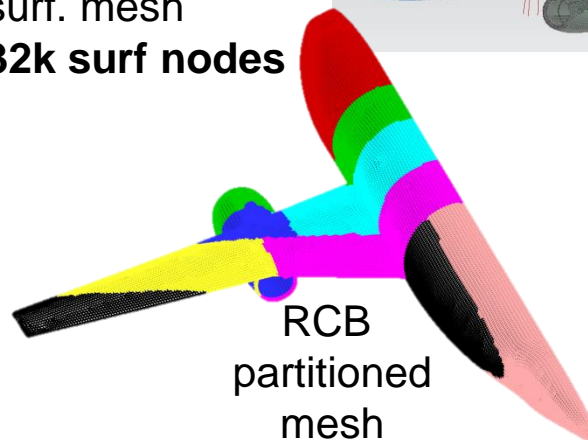
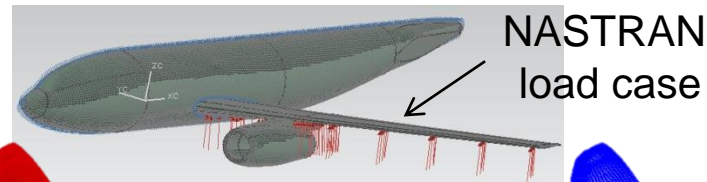
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Planned:

- RBF-based (MLS-type)

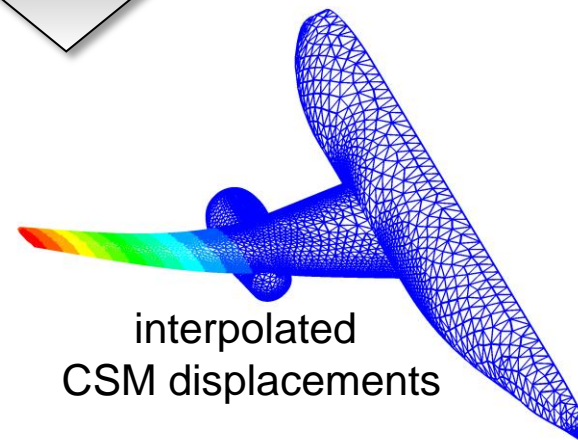
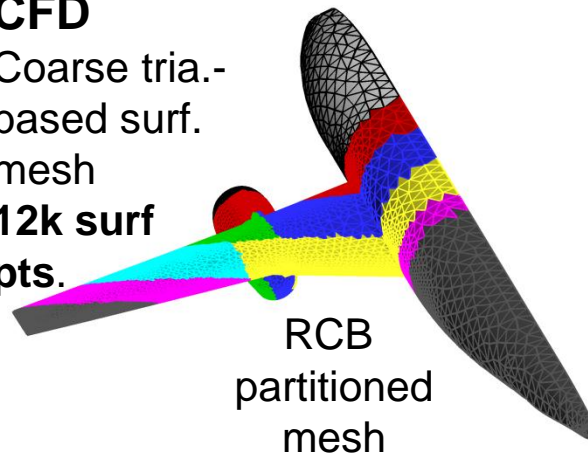
CSM

Quad.-based
surf. mesh
32k surf nodes



CFD

Coarse tria.-
based surf.
mesh
**12k surf
pts.**



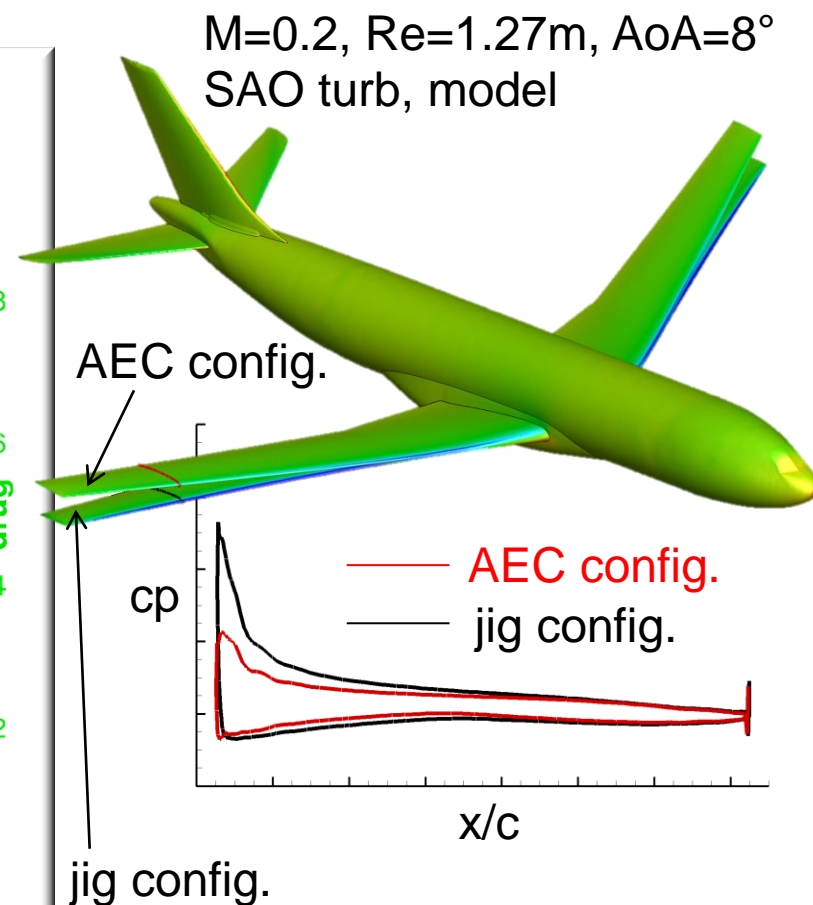
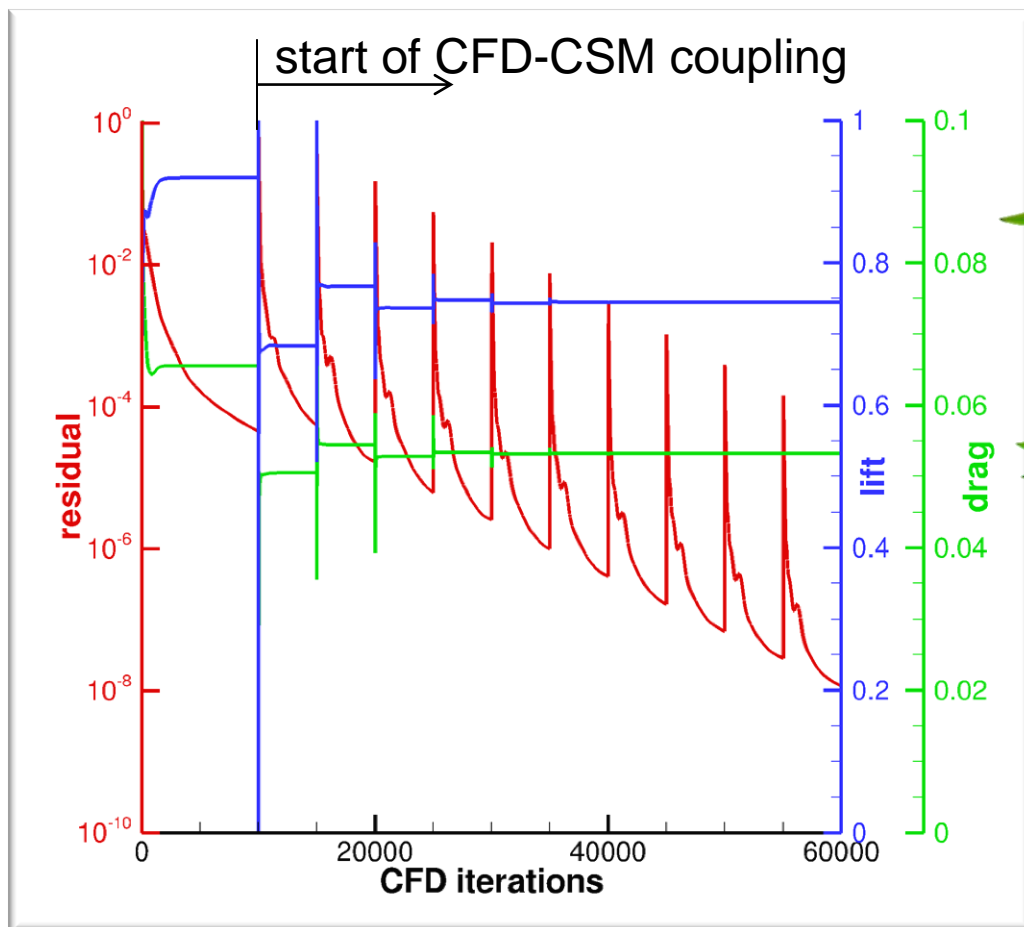
DLR F6 case

*part of FSDM (=open source)

Use case „F12“: Static Aeroelastic Simulation

FSTau + FSCouple + PyCSM + FSDeformation

20 CSD modes used, PyCSM on proc 0

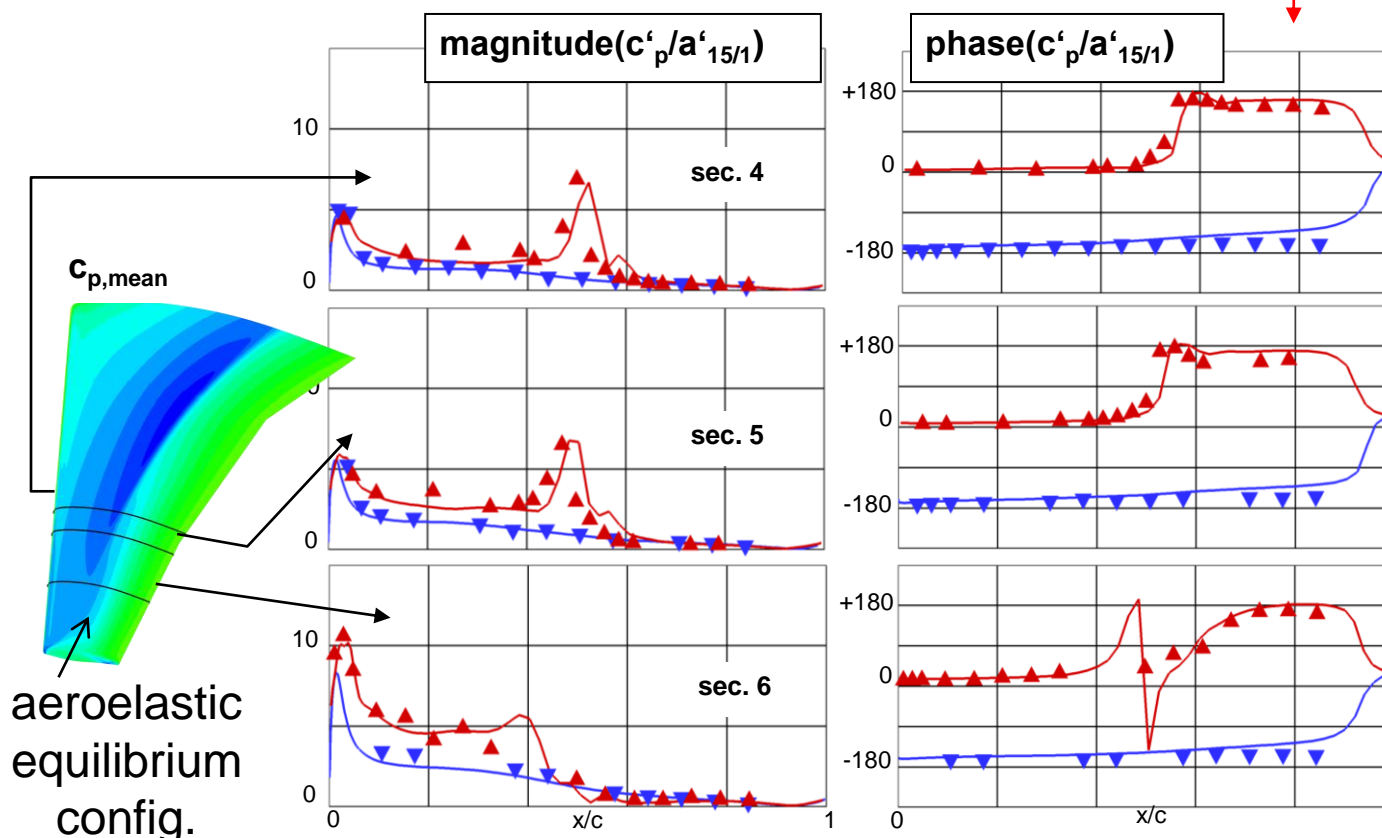
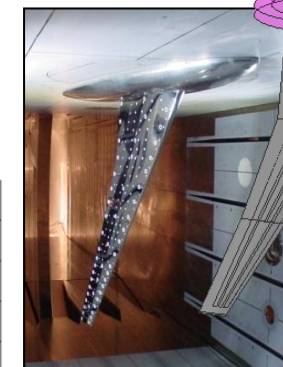
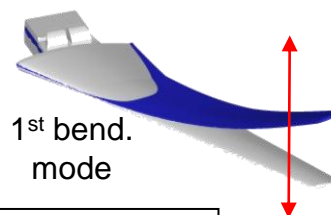


Use case „HIRENASD“: Dynamic Aeroelastic Simulation

FSTau + FSCouple + PyCSM + FSDeformation

Test 143:

- $M=0.8$, $Re=7m$, $\alpha=1.5$, $f_{exc}=26.92Hz$
- Excitation of 1st bending mode

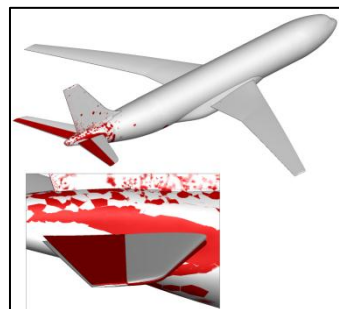


Results by courtesy of DLR
Institute for Aeroelasticity

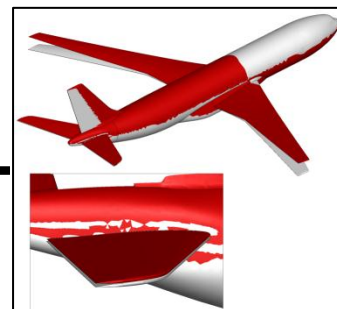


Current Work: Combination of Trim and CFD- CSD Coupling

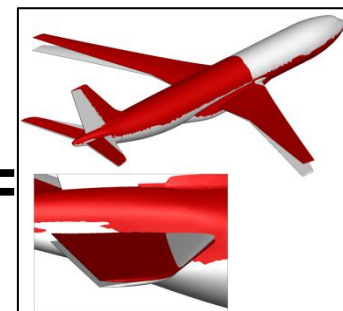
mesh A
„HTP rot.“



mesh B
„CSM defo.“



mesh A+B



Initial CFD-
CSM loop

TRIM LOOP

CONTROL FLOW

Inner CFD-
CSM loop

...
FSTau+
FSCouple+
PyCSM+
FSDeform.

FSTrim

FSMesh
Tools

FSDeform.

FSTau+
FSCouple+
PyCSM+
FSDeform.+
mesh A+B

CFD
mesh

defo. CFD
mesh
+ sol.

CL, CM_y
AoA, HTP

AoA, HTP,
CFD
mesh
Scat. data

Scat.
Data,
CFD
mesh

defo.
CFD
mesh
A

defo.
CFD
mesh
A

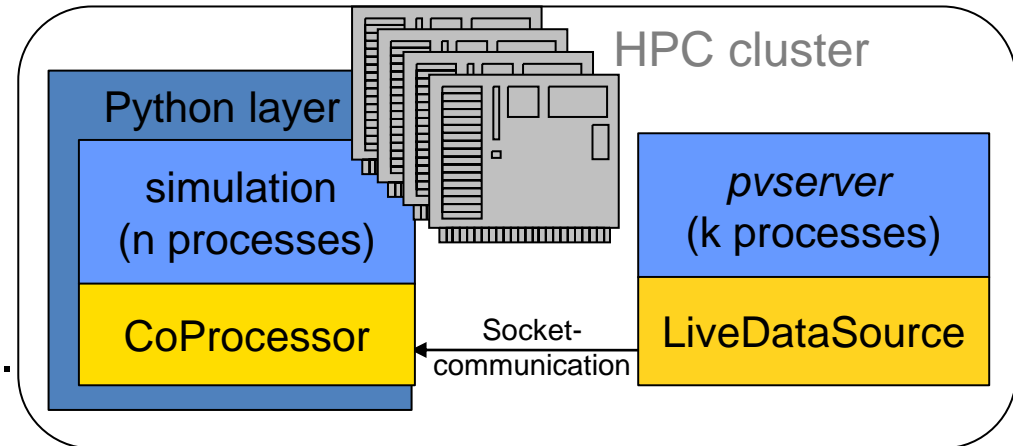
defo.
CFD
mesh
A+B + sol.

FSDM

Co-processing-based Visualisation

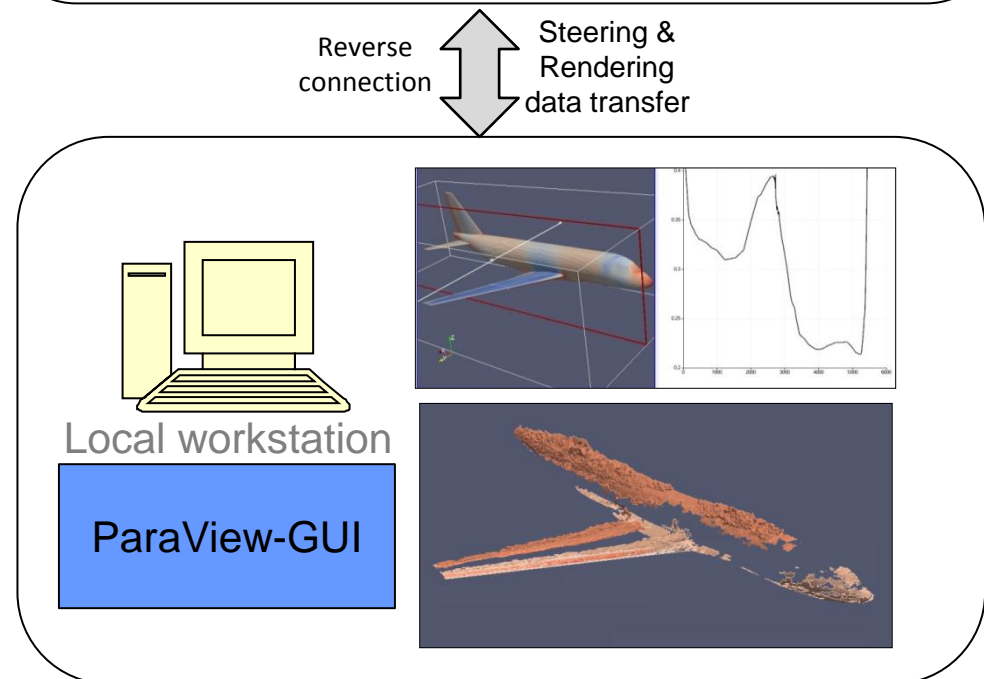
Benefits:

- Online monitoring
- Data reduction
- In parallel with sim.
w/o file I/O
- Parallel graphical data proc.

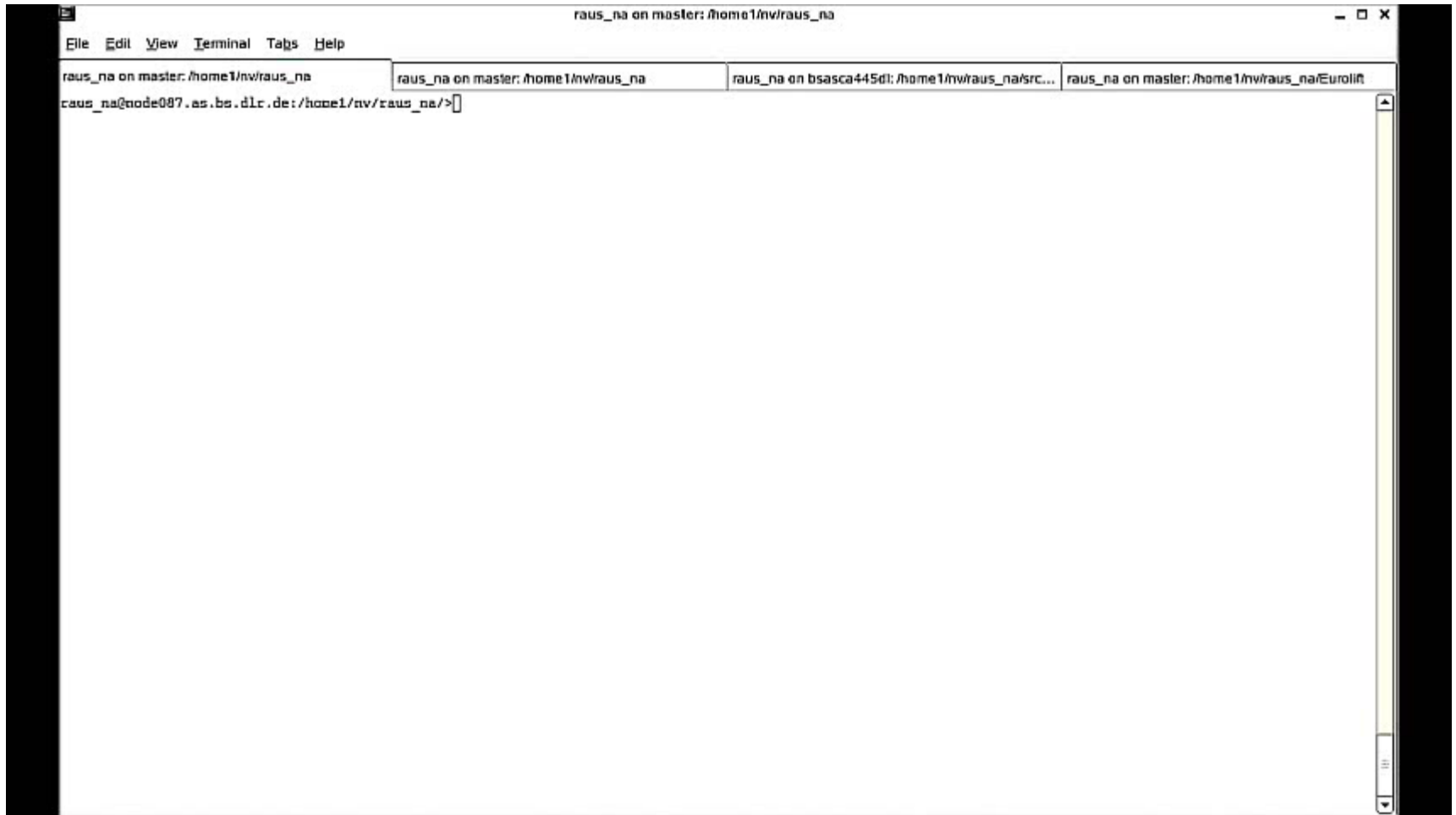


Implementation:

- Based on ParaView (version 3.9 + small own modifications)
- Uses ParaView-CoProcessing lib for Python-based integration in simulation
- FS interface available and applied at Airbus



Co-processing-based Visualisation: Demonstration



Summary

- Potential of FS demonstrated for multidisciplinary parallel analysis
- DLR strives to use FS for all multidisciplinary simulations in the near future
- DLR takes over maintenance of FSDeformation
- DLR will further develop FSTrim, FSDeformation, FSCouple, FSDM and will contribute FS6DoF
- With ongoing FS development more synergy effects of ONERA and DLR contributions can be expected



Examples of Currently Running Projects Involving DLR with Extense Usage and Development of FlowSimulator

- DLR project 
- German Aerospace Research Programme (LuFo) project 
- CFD4Loads project (initiated by Airbus)



...



End

